

1. $y(x) = c_1 e^{4x} + c_2 e^{-x}$
2. $y_p(x) = \frac{1}{2} e^{5x}$
3. $(D - 2)(D + 4)$ or $(D + 4)(D - 2)$ or $D^2 + 2D - 8$.
4. $y_p(x) = A \cos(2x) + B \sin(2x) + C x e^{2x}$
5. proof in book, Example 1, Sec. 10.1. Replace 1 with 2.
6. $y(t) = t e^{2t} + 2 e^{2t}$
7. $Y(s) = \frac{3s^2 + 6}{(s^3 + 2s + 1)}$
8. $f(t) = 3e^{-2t} \cos(4t) - \frac{5}{2} e^{-2t} \sin(4t)$
9. (a) Let $v = \dot{x}$. Then $\dot{v} = -2x - \frac{2}{5}v + \frac{F_0}{25} \cos(\gamma t)$.
 (b) Vector form: $\vec{x}' = \begin{bmatrix} 0 & 1 \\ -2 & -2/5 \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ \frac{F_0}{25} \cos(\gamma t) \end{bmatrix}$, where $\vec{x} = \begin{bmatrix} x \\ v \end{bmatrix}$.
 (c) $c_1 e^{-\frac{1}{5}t} \cos(\frac{7}{5}t) + c_2 e^{-\frac{1}{5}t} \sin(\frac{7}{5}t)$
10. $\begin{bmatrix} 2e^{3t} \cos(4t) - 5e^{3t} \sin(4t) \\ e^{3t} \cos(4t) \end{bmatrix}$
 Hint: use $e^{(3+4i)t} = e^{3t}(\cos(4t) + i \sin(4t))$, multiply, and collect real and imaginary parts. For this test question, ignore the imaginary parts.
11. Eigenvector for or eigenvalue $1 + 2i$: $\begin{bmatrix} 1 \\ -i \end{bmatrix}$
 (or any (complex) multiple of it, like $\begin{bmatrix} i \\ 1 \end{bmatrix}$)
12. $\vec{x}(t) = c_1 e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ -3 \end{bmatrix}$
 Note that you need not compute the eigenvalues from scratch since I gave you two eigenvectors. You merely need to multiply the matrix $\begin{bmatrix} 2 & 1 \\ 0 & -1 \end{bmatrix}$ by each eigenvector to see which eigenvalue corresponds to which eigenvector. Since the matrix is upper triangular, then the eigenvalues of 2 and -1 are the diagonal elements.
13. (Extra Credit) Since y_1 and y_2 are known solutions to $L[y] = 0$, then $y_1'' + 5y_1' - 3y_1 = 0$ and $y_2'' + 5y_2' - 3y_2 = 0$. Therefore, $L[c_1 y_1 + c_2 y_2] = (c_1 y_1 + c_2 y_2)'' + 5(c_1 y_1 + c_2 y_2)' - 3(c_1 y_1 + c_2 y_2) = c_1(y_1'' + 5y_1' - 3y_1) + c_2(y_2'' + 5y_2' - 3y_2) = c_1 \cdot 0 + c_2 \cdot 0 = 0$. That is, $c_1 y_1 + c_2 y_2$ is a solution to $L[y] = 0$.