# An Algorithm to Generate Repeating Hyperbolic Patterns 

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The $\{\mathbf{8 , 3}\}$ tessellation on Circle Limit III


## An Islamic pattern based on the $\{8,3\}$ tessellation



## Poincaré Circle Model of Hyperbolic Geometry



- Points: points within the bounding circle
- Lines: circular arcs perpendicular to the bounding circle (including diameters as a special case)


## The Regular Tessellations $\{\mathbf{p}, \mathbf{q}\}$

There is a regular tessellation, $\{p, q\}$ of the hyperbolic plane by regular $\boldsymbol{p}$-sided polygons meeting $\boldsymbol{q}$ at a vertex provided
$(p-2)(q-2)>4$


The tessellation $\{6,4\}$ superimposed on the Circle Limit I pattern.

# An arabesque pattern based on the $\{6,4\}$ tessellation 



## The General Replication Algorithm

A motif is a basic sub-pattern, of which the entire repeating pattern is comprised.

Replication is the process of transforming copies of the motif about the hyperbolic plane in order to create the whole repeating pattern.
A fundamental region for the symmetry group of a pattern is a closed topological disk such that copies of it cover the plane without gaps or overlaps.

In Escher patterns the motif can usually be used as a fundamental region.

For a pattern with a finite motif, the fundamental region can be taken to be a convex polygon. This polygon will contain exactly the right pieces of the motif to reconstruct it.
Replication using copies of such a fundamental polygon will also create the entire pattern of motifs.

## A Fundamental Polygon Tessellation

A quadrilateral can used as the fundamental region for the Circle Limit III pattern, as shown below


## Layers of Fundamental Polygons

The fundamental polygons are arranged in layers (also called coronas in tiling literature), which are defined inductively.

The first layer consists of all polygons with a vertex at the center of the bounding circle.

The boldmath $k+1^{\text {st }}$ layer consists of all polygons sharing an edge or vertex with the $k^{\text {th }}$ layer (and no previous layers).

## A Polygon Tessellation Showing Layers



The polygon tessellation, with a fundamental polygon emphasized and parts of layers 1,2 , and 3 labeled.

## Specification of the Fundamental Polygon

We use $\left\{\boldsymbol{p} ; \boldsymbol{q}_{1}, \boldsymbol{q}_{2}, \ldots, \boldsymbol{q}_{p}\right\}$ to denote the fundamental polygon with $\boldsymbol{p}$ sides and $\boldsymbol{q}_{i}$ polygons meeting at vertex $\boldsymbol{i}$ (so the interior angle at the $i^{\text {th }}$ vertex is $2 \pi / q_{i}$ ).

The condition that a polygon is a fundamental polygon for a hyperbolic tessellation is that:

$$
\sum_{i=1}^{p} \frac{1}{q_{i}}<\frac{p}{2}-1
$$

(which generalizes the condition $(p-2)(q-2)>4$ for regular tessellations). If the " $<$ " is replaced with " $=$ " or " ">", one obtains a Euclidean or spherical tessellation respectively.

We say a polygon of a tessellation has minimal exposure if it shares an edge with a previous layer; we say it has minimal exposure if it shares a vertex with a previous layer.

## Minimal and Maximal Exposure



The polygons with minimal exposure are marked with $\boldsymbol{m}$ 's, and those with maximal exposure are marked with M's.

## Some Polygons and Replication



This figure shows how recursive calls in the replication work starting at polygon A. Polygon vertices are numbered in counter-clockwise order with vertex $i$ at the right end of edge $i$ looking outward.

## The Top-level 'Driver" for Replication

The replication process starts with the following toplevel "driver", which calls the recursive routine replicateMotif() to create the rest of the pattern.

```
replicate ( motif )
{
    for ( j = 1 to q[1] )
    {
            qTran = edgeTran[1] ;
            replicateMotif(motif,qTran,2,MAX_EXP);
            qTran = addToTran ( qTran, -1 ) ;
    }
}
```


## Utilities to Support Replication

Functions to compute transformations, based on tranMult () which multiplies two transformations and returns the product.
addToTran ( tran, shift ) \{
if ( shift \% p == 0 ) return tran ; else return computeTran (tran, shift); \}
computeTran ( tran, shift ) $\{$

$$
\begin{aligned}
\text { newEdge }= & \text { (tran.pPosition + } \\
& \text { tran.orientation*shift) \%p ; }
\end{aligned}
$$

return tranMult (tran, edgeTran[newEdge] ) ;
\}

## Arrays that control replication.

$$
\left.\begin{array}{lll}
\text { pShiftArray[] } & =\{1, r & 0
\end{array}\right\} ;
$$

## The Recursive replicateMotif()

```
replicateMotif(motif, inTran, layer, exposure)
{
    drawMotif ( motif, inTran ) ;
    if ( layer < maxLayers )
    {
        pShift = pShiftArray[exposure] ;
        verticesToDo = p -
                verticesToSkipArray[exposure] ;
        for ( i = 1 to verticesToDo )
        {
            pTran = computeTran(initialTran, pShift) ;
            first_i = ( i == 1 ) ;
            qTran = addToTran(pTran, qShiftArray[first_i]) ;
            if ( pTran.orientation > 0 )
            vertex = (pTran.pposition-1) % p ;
        else
            vertex = pTran.pposition ;
        polygonsToDo = q[vertex] -
                                    polygonsToSkipArray[first_i] ;
    for ( j = 1 to polygonsToDo )
        {
            first_j = ( j == 1 ) ;
            newExpose = exposureArray[first_j] ;
            replicateMotif(motif, qTran, layer+1, newExpose) ;
            qTran = addToTran ( qTran, -1 ) ;
        }
        pShift = (pShift + 1) % p ;
        }
    }
}
```



## A "Three Element" Pattern with Different Numbers of Animals Meeting at their Heads



## A "Three Element" Pattern with 3 Bats, 5 Lizards, and 4 Fish Meeting at their Heads



## A "Three Element" Pattern with 3 Bats, 5 Lizards, and 4 Fish Meeting at their Heads



## Future Work

- Allow vertices at infinity.
- Create a program to transform between different fundamental polygons.
- Automatically generate patterns with color symmetry.

