

SubTile 2013, Marseille

An Algorithm to Create Hyperbolic Escher Tilings

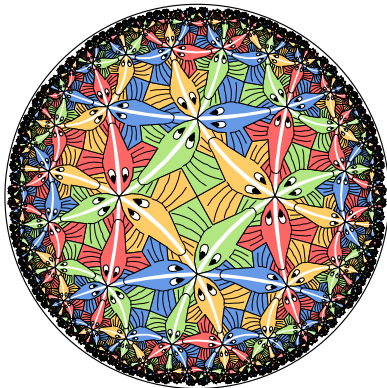
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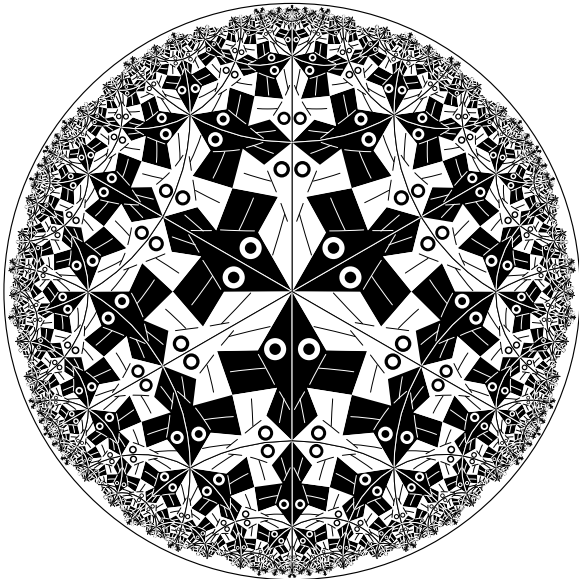
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Outline

- ▶ Motivation — M.C. Escher examples
- ▶ Hyperbolic geometry, Repeating patterns, and regular tessellations
- ▶ The replication algorithm
- ▶ Other hyperbolic patterns inspired by Escher patterns
- ▶ Future research

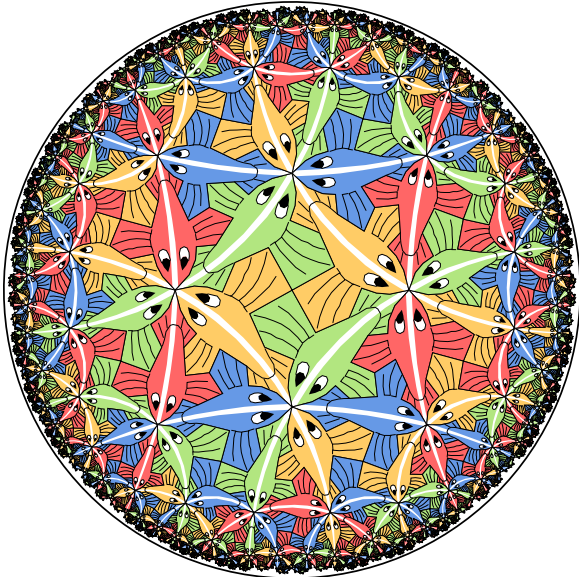
Hyperbolic Art Pioneer: M.C. Escher
Four “Circle Limit” Patterns: Circle Limit I



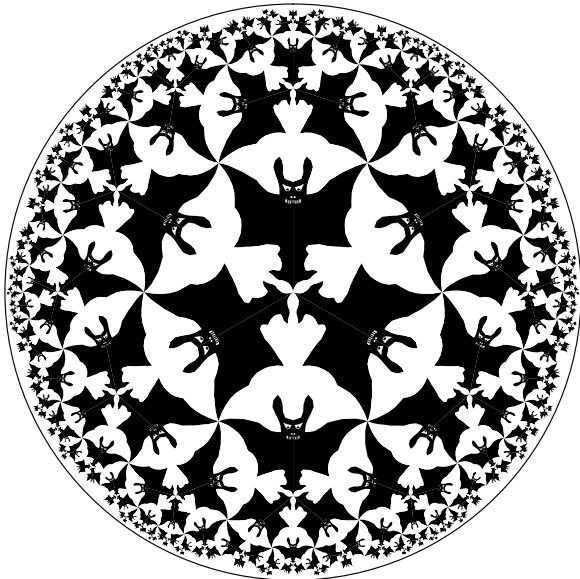
Circle Limit II



Circle Limit III



Circle Limit IV

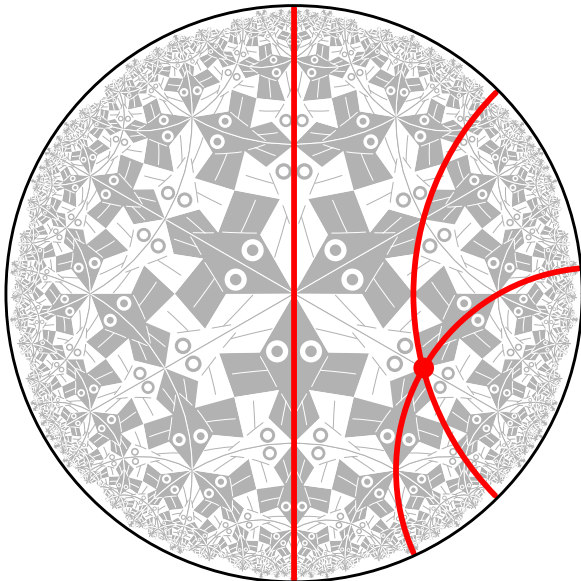


Creating Repeating Hyperbolic Patterns

A two-step process:

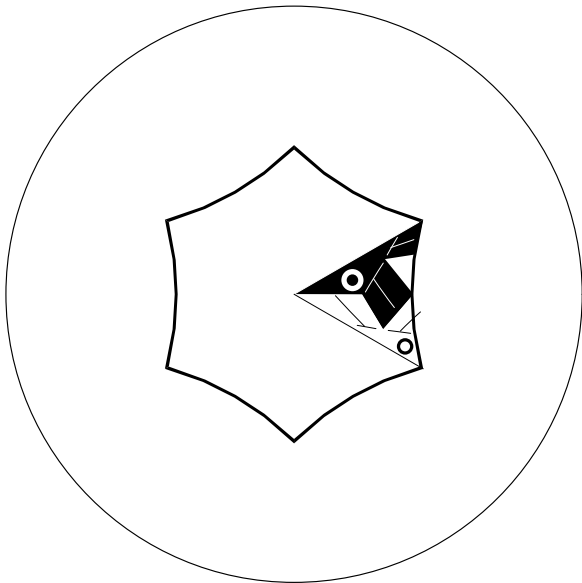
- 1. Design the fundamental tile or motif**
- 2. Transform copies of the tile about the hyperbolic plane:
replication**

Poincaré Disk Model of Hyperbolic Geometry



Repeating Patterns

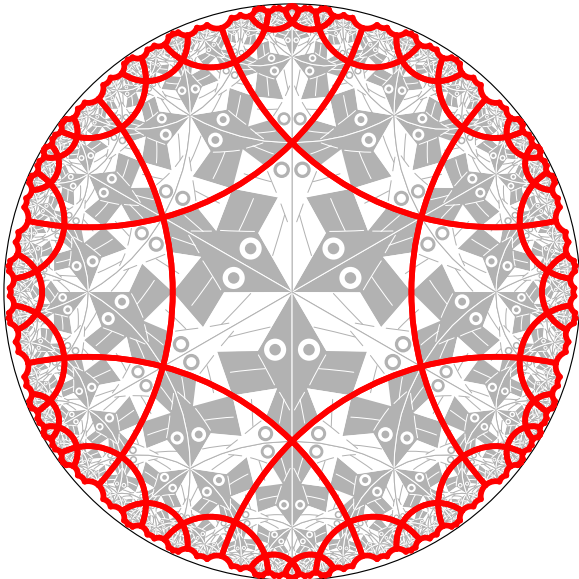
A repeating pattern is composed of congruent copies of the motif.



The Regular Tessellations $\{p, q\}$

- ▶ **The regular tessellation $\{p, q\}$ is a tiling composed of regular p -sided polygons, or p -gons meeting q at each vertex.**
- ▶ **It is necessary that $(p - 2)(q - 2) > 4$ for the tessellation to be hyperbolic.**
- ▶ **If $(p - 2)(q - 2) = 4$ or $(p - 2)(q - 2) < 4$ the tessellation is Euclidean or spherical respectively.**

The Regular Tessellation $\{6, 4\}$



A Table of the Regular Tessellations

q	$p=3$	$p=4$	$p=5$	$p=6$	$p=7$	$p=8$...
8	*	*	*	*	*	*	...
7	*	*	*	*	*	*	...
6	□	*	*	*	*	*	...
5	○	*	*	*	*	*	...
4	○	□	*	*	*	*	...
3	○	○	○	□	*	*	...

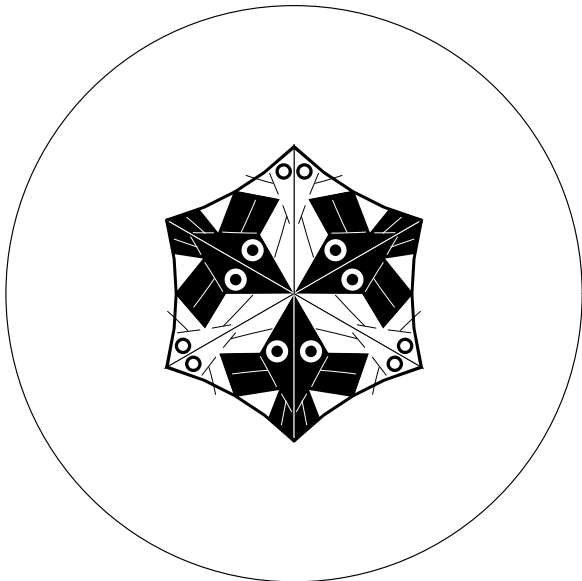
□ - Euclidean tessellations
 ○ - spherical tessellations
 * - hyperbolic tessellations

The Replication Algorithm

To reduce the number of transformations and to simplify the replication process, we form the p -gon pattern from all the copies of the motif touching the center of the bounding circle.

- ▶ Thus in order to replicate the pattern, we apply transformations to the p -gon pattern rather than to each individual motif.
- ▶ Some parts of the p -gon pattern may protrude from the enclosing p -gon, as long as there are corresponding indentations, so that the final pattern will fit together like a jigsaw puzzle.
- ▶ The p -gon pattern is often called the translation unit in repeating Euclidean patterns.

The p -gon pattern for Circle Limit I



Layers of p-gons

We note that the p-gons of a $\{p, q\}$ tessellation are arranged in layers as follows:

- ▶ The first layer is just the central p-gon.
- ▶ The $k + 1^{st}$ layer consists of all p-gons sharing an edge or a vertex with a p-gon in the k^{th} layer (and no previous layers).
- ▶ Theoretically a repeating hyperbolic pattern has an infinite number of layers, however if we only replicate a small number of layers, this is usually enough to appear to fill the bounding circle to our Euclidean eyes.

Exposure of a p-gon

We also define the exposure of a p-gon in terms of the number of edges it has in common with the next layer (and thus the fewest edges in common with the previous layer).

- ▶ A p-gon has maximum exposure if it has the most edges in common with the next layer, and thus only shares a vertex with the previous layer.
- ▶ A p-gon has minimum exposure if it has the least edges in common with the next layer, and thus shares an edge with the previous layer.
- ▶ We abbreviate these values as MAX_EXP and MIN_EXP respectively.

The Replication Algorithm

The replication algorithm consists of two parts:

- ▶ A top-level “driver” routine `replicate()` that draws the first layer, and calls a second routine, `recursiveRep()`, to draw the rest of the layers.
- ▶ A routine `recursiveRep()` that recursively draws the rest of the desired number of layers.

A tiling pattern is determined by how the p-gon pattern is transformed across p-gon edges. These transformations are in the array `edgeTran[]`

The Top-level Routine replicate()

```
Replicate ( motif ) {  
    drawPgon ( motif, IDENT ) ; // Draw central p-gon  
    for ( i = 1 to p ) { // Iterate over each vertex  
        qTran = edgeTran[i-1] ;  
        for ( j = 1 to q-2 ) { // Iterate about a vertex  
            exposure = (j == 1) ? MIN_EXP : MAX_EXP ;  
            recursiveRep ( motif, qTran, 2, exposure ) ;  
            qTran = addToTran ( qTran, -1 ) ;  
        }  
    }  
}
```

The function addToTran() is described next.

The Function `addToTran()`

Transformations contain a matrix, the orientation, and an index, `pPosition`, of the edge across which the last transformation was made (`edgeTran[i].pPosition` is the edge matched with edge `i` in the tiling). Here is `addToTran()`:

```
addToTran ( tran, shift ) {  
    if ( shift % p == 0 ) return tran ;  
    else return computeTran ( tran, shift ) ;  
}
```

where `computeTran()` is:

```
computeTran ( tran, shift ) {  
    newEdge = (tran.pPosition +  
               tran.orientation * shift) % p ;  
    return tranMult(tran, edgeTran[newEdge]) ;  
}
```

and where `tranMult (t1, t2)` multiplies the matrices and orientations, sets the `pPosition` to `t2.pPosition`, and returns the result.

The Routine recursiveRep()

```
recursiveRep ( motif, initialTran, layer, exposure ) {  
  DrawPgon ( motif, initialTran ) ; // Draw p-gon pattern  
  if ( layer < maxLayer ) { // If any more layers  
    pShift = ( exposure == MIN_EXP ) ? 1 : 0 ;  
    verticesToDo = ( exposure == MIN_EXP ) ? p-3 : p-2 ;  
    for ( i = 1 to verticesToDo ) { // Do each vertex  
      pTran = computeTran ( initialTran, pShift ) ;  
      qSkip = ( i == 1 ) ? -1 : 0 ;  
      qTran = addToTran ( pTran, qSkip ) ;  
      pgonsToDo = ( i == 1 ) ? q-3 : q-2 ;  
      for ( j = 1 to pgonsToDo ) { // Go around a vertex  
        newExposure = ( j == 1 ) ? MIN_EXP : MAX_EXP ;  
        recursiveRep(motif, qTran, layer+1, newExposure);  
        qTran = addToTran ( qTran, -1 ) ;  
      }  
      pShift = (pShift + 1) % p ; // Go to next vertex  
    }  
  }  
}
```

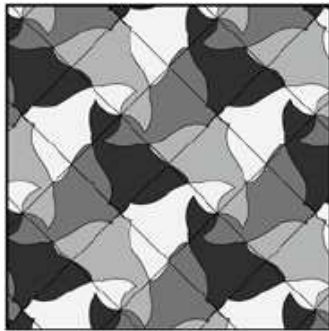
Special Cases

The algorithm above works for $p > 3$ and $q > 3$.

If $p = 3$ or $q = 3$, the same algorithm works, but with different values of `pShift`, `verticesToDo`, `qSkip`, etc.

Sample Patterns

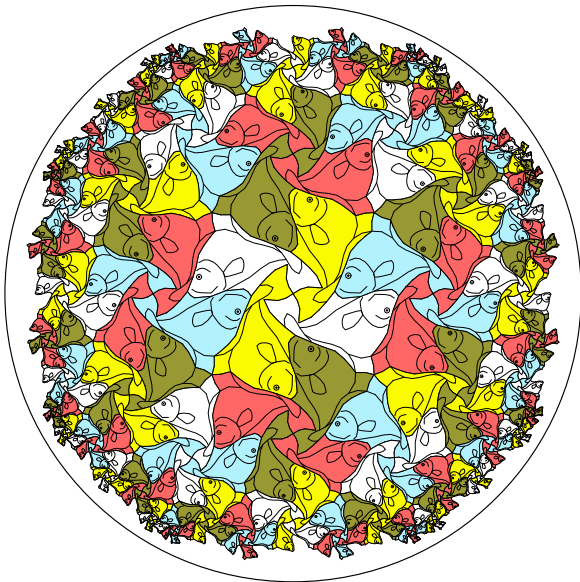
Escher's Euclidean Notebook Drawing 20, based on the $\{4, 4\}$ tessellation.



Escher's Spherical Fish Pattern Based on $\{4, 3\}$



A Hyperbolic Fish Pattern Based on $\{4, 5\}$



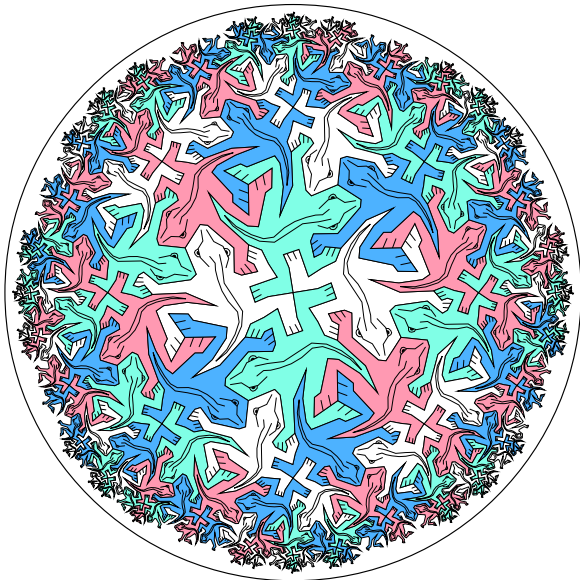
Escher's Euclidean Notebook Drawing 25, based on the $\{6, 3\}$ tessellation.



Escher's Print Reptiles based on Notebook Drawing 25



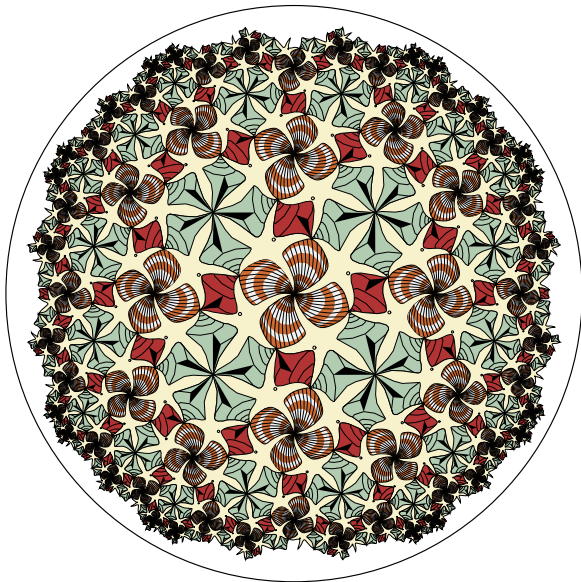
A Hyperbolic Lizard Pattern Based on $\{8, 3\}$



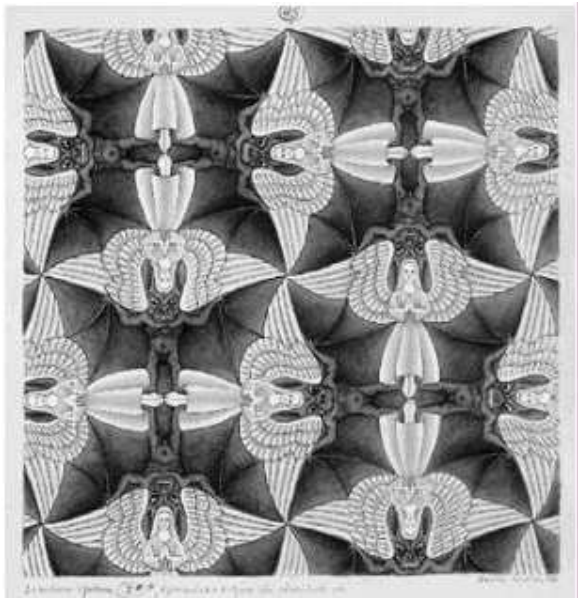
Escher's Euclidean Notebook Drawing 42, based on the $\{4,4\}$ tessellation.



A Hyperbolic Shell Pattern Based on $\{4, 5\}$



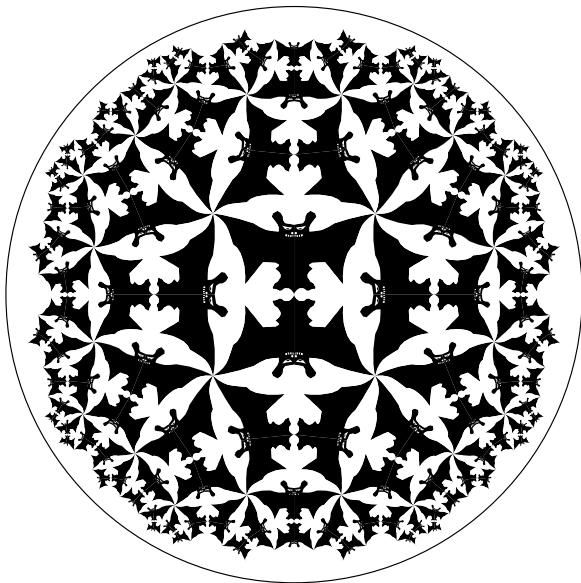
Escher's Euclidean Notebook Drawing 45, based on the $\{4,4\}$ tessellation.



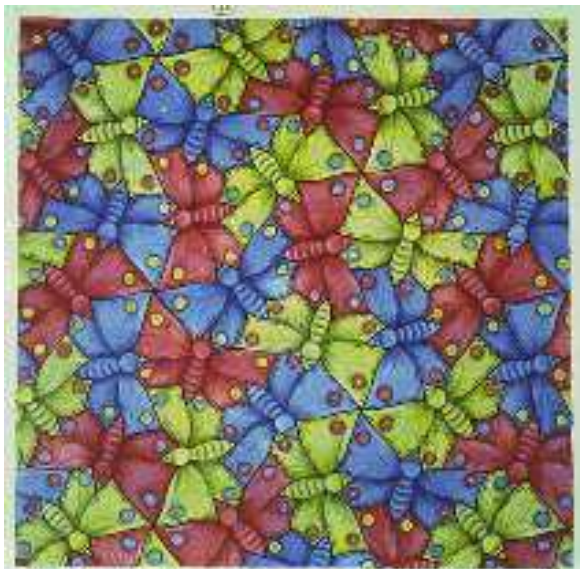
Escher's Spherical "Heaven and Hell" Based on $\{4, 3\}$



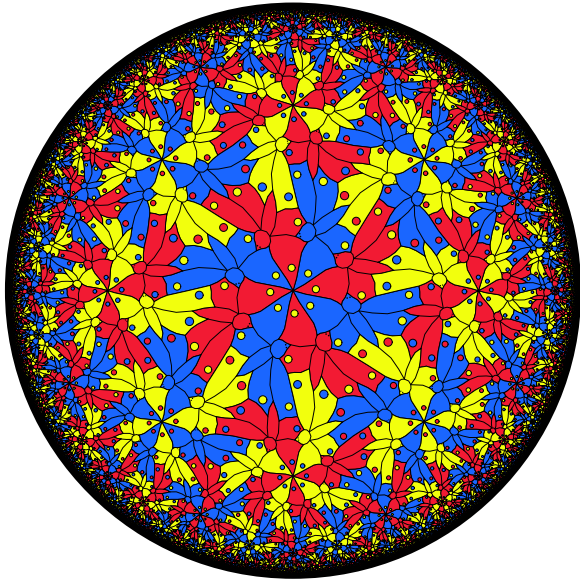
A Hyperbolic “Heaven and Hell” Pattern Based on $\{4, 5\}$



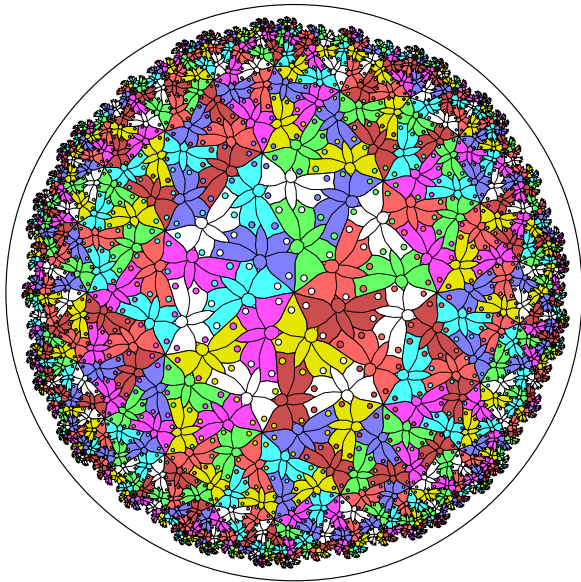
Escher's Euclidean Notebook Drawing 70, based on the $\{6, 3\}$ tessellation.



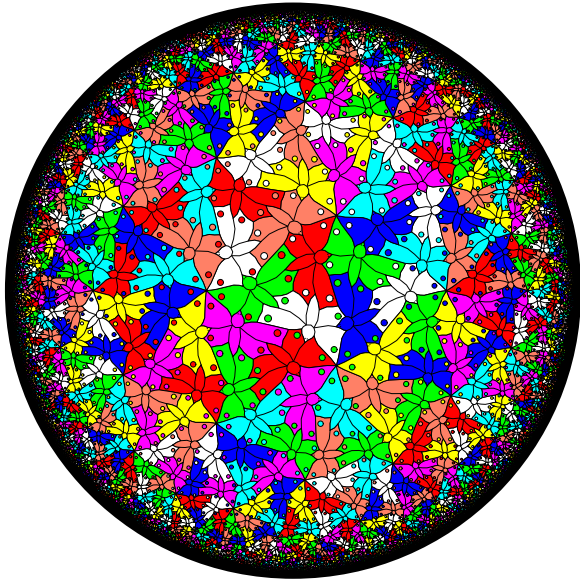
A Hyperbolic Butterfly Pattern Based on $\{8, 3\}$



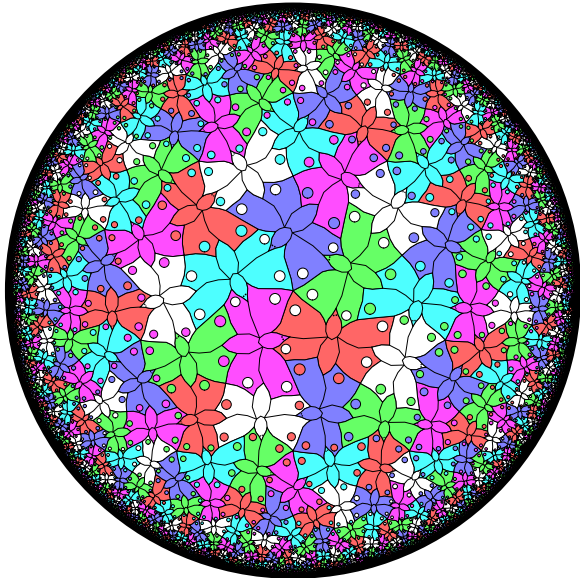
A Hyperbolic Butterfly Pattern Based on $\{7, 3\}$



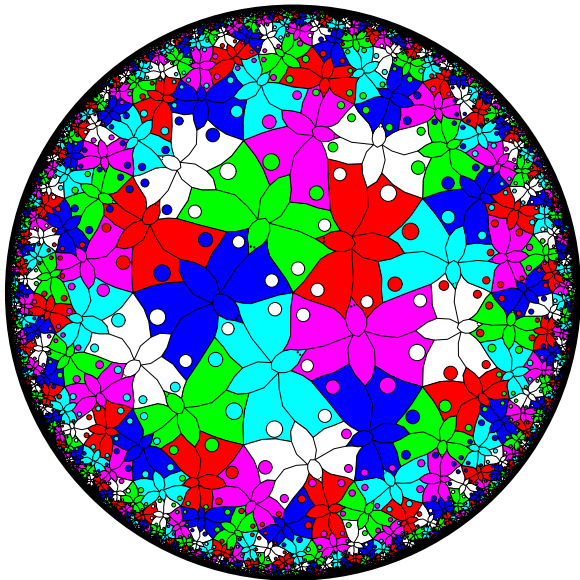
A Hyperbolic Butterfly Pattern Based on $\{3, 7\}$



A Hyperbolic Butterfly Pattern Based on $\{5, 4\}$



A Hyperbolic Butterfly Pattern Based on $\{5, 5\}$



Future Work

- ▶ Extend the algorithm to handle tilings by non-regular polygons.
- ▶ Extend the algorithm to the cases infinite regular polygons: $\{p, \infty\}$ of infinite p -sided polygons, or $\{\infty, q\}$ of infinite-sided polygons meeting q at a vertex.
- ▶ Create a program to transform between different fundamental polygons.
- ▶ Automatically generate patterns with color symmetry.

Thank You

To CIRM and all the organizers of SubTile 2013

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