#### Signal – A function of time

# System – Processes input signal (excitation) and produces output signal (response)





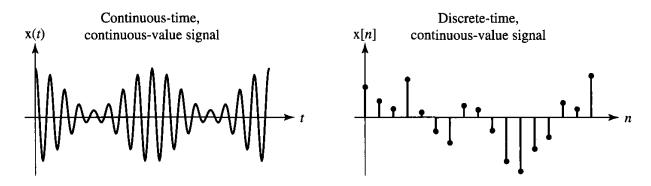
- 1. Types of signals
- 2. Going from analog to digital world
- 3. An example of a system
- 4. Mathematical representation of signals



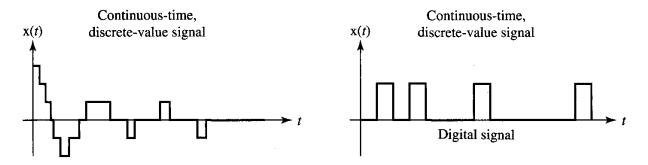
# Types of Signals

|   | Time       | Value      |           |
|---|------------|------------|-----------|
| 1 | Continuous | Continuous | - Analog  |
| 2 | Continuous | Discrete   | - Digital |
| 3 | Discrete   | Continuous |           |
| 5 | Discrete   | Discrete   |           |





**Figure 1.3** Examples of continuous-time and discrete-time signals.



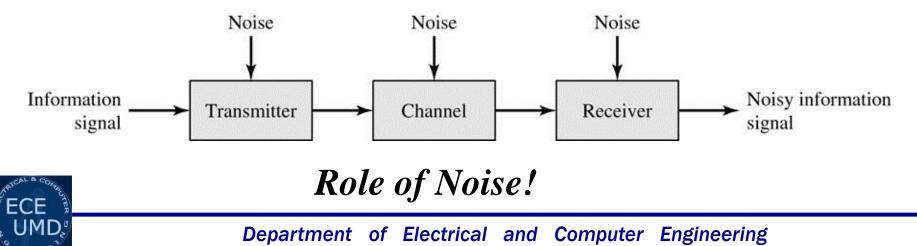
**Figure 1.4** Examples of continuous-time and digital signals.

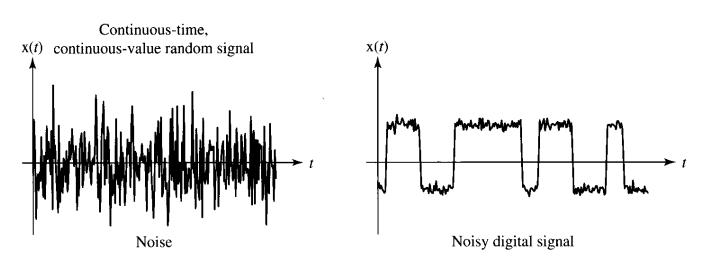


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# Types of Signals

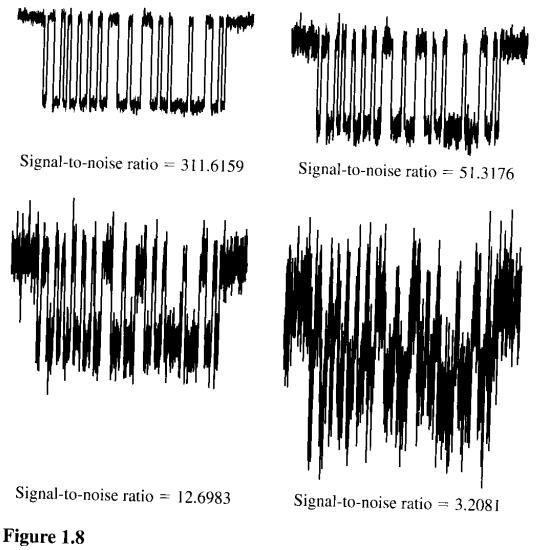
| Time       | Value                                |   |
|------------|--------------------------------------|---|
| Continuous | Continuous                           | Analog  |
| Continuous | Discrete                             | - Digital   |
| Discrete   | Continuous                           |   |
| Discrete   | Discrete                             | -   |
|            | Continuous<br>Continuous<br>Discrete | Continuous       Continuous         Continuous       Discrete         Discrete       Continuous |





**Figure 1.5** Examples of noise and a noisy digital signal.

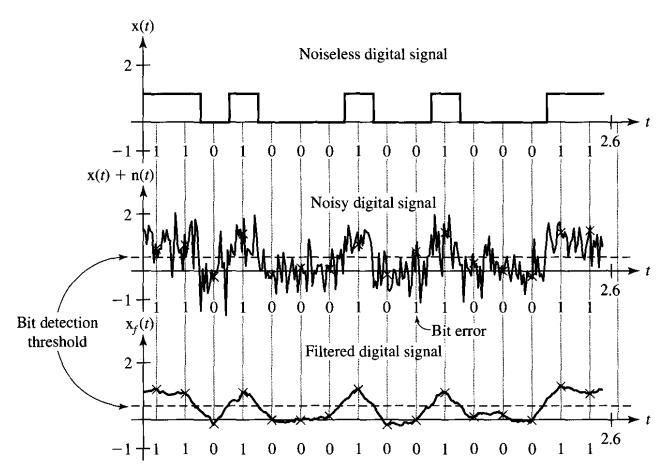




Noisy digital ASCII signal.

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# Advantage of Digital World





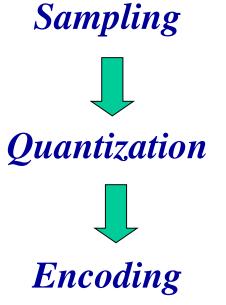
Use of a filter to reduce bit error rate in a digital signal.

-- ( +)



# Going from Analog to Digital World

**Three Step Process** 





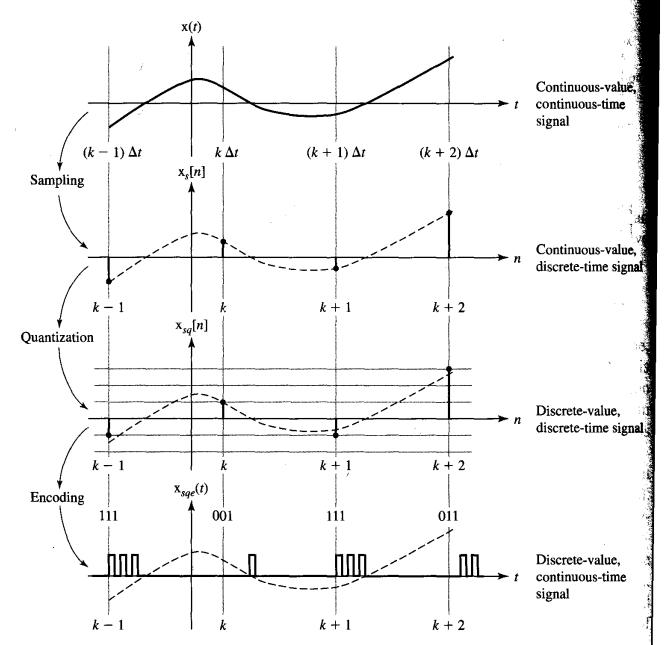
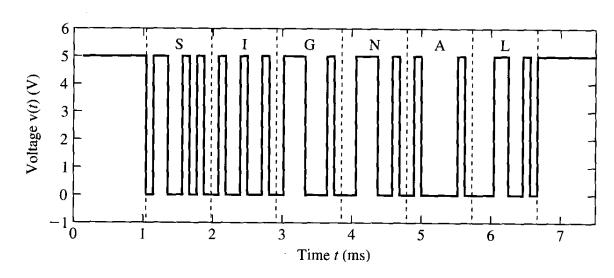




Figure 1.6 Sampling, quantization, and encoding of a signal to illustrate various signal types.





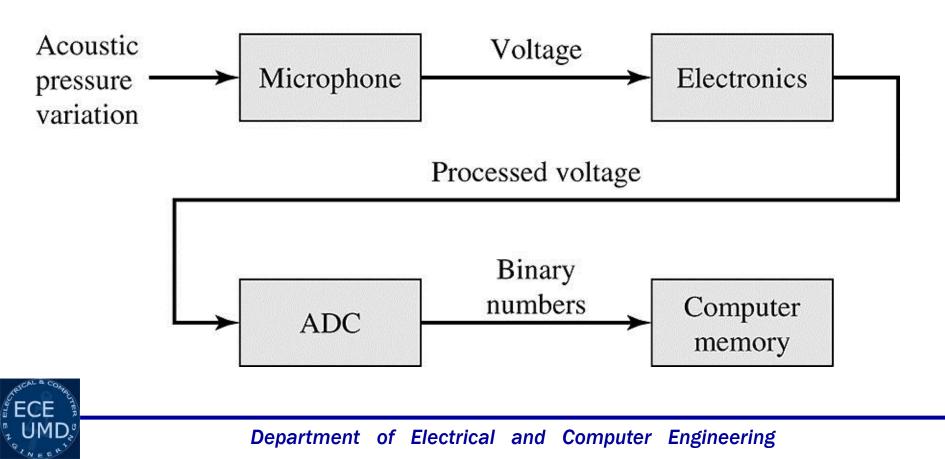
Asynchronous serial binary ASCII-encoded voltage signal for the message "SIGNAL"



# **Example of System**

#### A simple system example – Sound Recording System

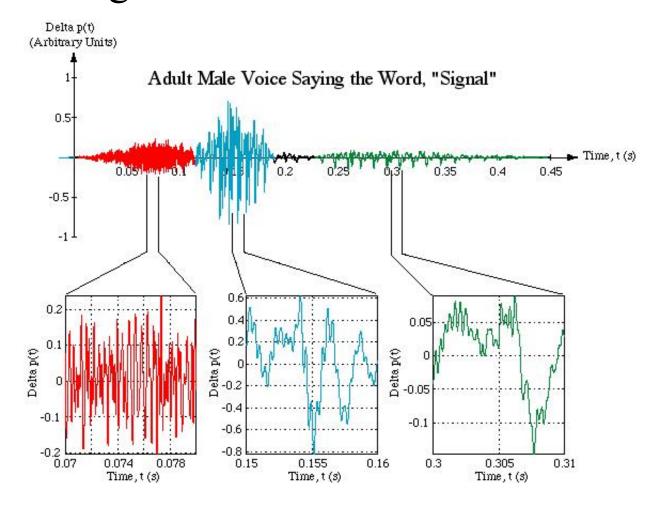
What constitutes a sound recording system?



# **Recorded Sound as a Signal Example**

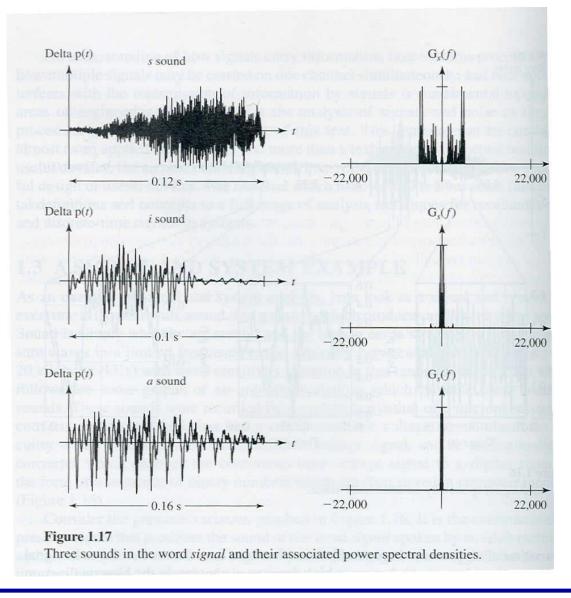
• "s" "i" "gn" "al"

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# **Representation of Signals**





#### Frequency Domain



#### Another Example of System

#### A very complex system example – Human Brain

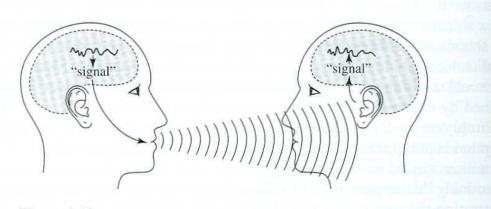


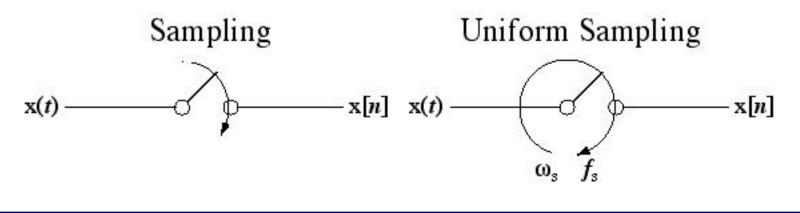
Figure 1.18 Communication between two people involving signals and signal processing by systems.



# Sampling a CT Signal to Create a DT Signal

- Sampling is acquiring the values of a CT signal at discrete points in time
- x(t) is a CT signal --- x[n] is a DT signal

 $x[n] = x(nT_s)$  where  $T_s$  is the time between samples



## Mathematical Representation of Signals

**Continuous Time** 

$$x(t) = A\sin(\omega_0 t)$$

 $=A\sin(2\pi f_0 t)$ 

Discrete Time  $x[nT_{s}] = A \sin[\omega_{o}nT_{s}]$   $= A \sin[2\pi f_{o}nT_{s}]$ 



## **Continuous Time Signals**



$$=A\sin(2\pi f_o t)$$

$$=A\sin(\frac{2\pi t}{T_o})$$

$$g(t) = C\cos(2\pi f_o t + \theta)$$



*Review of Euler's Identity – Complex valued sinusoidal signals* 

**Euler's Identity** 

$$e^{j2\pi f_F t} = \cos(2\pi f_F t) + j\sin(2\pi f_F t)$$

Also

$$e^{-j2\pi f_F t} = \cos(2\pi f_F t) - j\sin(2\pi f_F t)$$

$$\Rightarrow \cos(2\pi f_F t) = \frac{e^{j2\pi f_F t} + e^{-j2\pi f_F t}}{2}$$

and

$$\Rightarrow \sin(2\pi f_F t) = \frac{e^{j2\pi f_F t} - e^{-j2\pi f_F t}}{2j}$$



#### **Review of Euler's Identity – Complex valued sinusoidal signals**

Euler's Identity  

$$Ce^{j(2\pi f_F t + \theta)} = C\cos(2\pi f_F t + \theta) + jC\sin(2\pi f_F t + \theta)$$
Also

$$Ce^{-j(2\pi f_F t + \theta)} = C\cos(2\pi f_F t + \theta) - jC\sin(2\pi f_F t + \theta)$$

$$\Rightarrow C\cos(2\pi f_F t + \theta) = \frac{Ce^{j(2\pi f_F t + \theta)} + Ce^{-j(2\pi f_F t + \theta)}}{2}$$

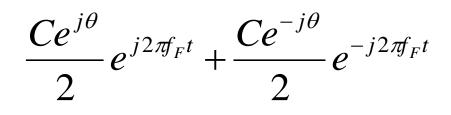
and

$$\Rightarrow C\cos(2\pi f_F t + \theta) = \frac{Ce^{j\theta}}{2}e^{j2\pi f_F t} + \frac{Ce^{-j\theta}}{2}e^{-j2\pi f_F t}$$



Three ways to represent a sinusoidal frequency  $f_F$ 

Method 1:



Method 2:

$$C\cos(2\pi f_F t + \theta)$$

Method 3:

$$A\cos(2\pi f_F t) + B\sin(2\pi f_F t)$$

Where

$$C = \sqrt{A^2 + B^2} \qquad \theta = \tan^{-1} - \frac{B}{A}$$

# **Exponential Functions**

$$g(t) = Ae^{\sigma t}$$

$$g(t) = Ae^{-\sigma t}$$

Complex valued exponential signal:

$$g(t) = Ae^{(\sigma + j\omega)t} = Ae^{\sigma t} [\cos \omega t + j\sin \omega t]$$

Where do these functions occur in real life?



# Discontinuity of a function

**Definition:** 
$$\lim_{\varepsilon \to 0} g(t + \varepsilon) \neq \lim_{\varepsilon \to 0} g(t - \varepsilon)$$

Simple words:

If the value of function is different at time  $t_0$  when approached at  $t_0$  by decreasing and increasing time, then the function is discontinuous at time  $t_0$ 

**Examples:** 



# **Unit Step Function**

Definition:  $u(t) = \begin{cases} 1 & t > 0 \\ 1/2 & t = 0 \\ 0 & t < 0 \end{cases}$ 

**Real Physical Phenomenon:** 

Switching



# Signum Function

**Definition:** 

$$sgn(t) = \begin{cases} 1 & t > 0 \\ 0 & t = 0 \\ -1 & t < 0 \end{cases}$$

=2u(t)-1



# **Ramp Function**

**Definition:** 

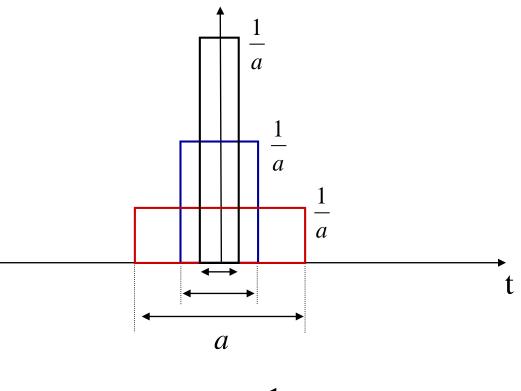
$$ramp(t) = \begin{cases} t & t > 0 \\ 0 & t \le 0 \end{cases}$$

=tu(t)

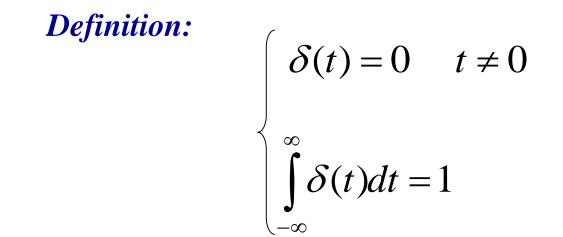
$$=\int_{-\infty}^{t}u(x)dx$$

Can you generate this function?

## **Unit Impulse Function**



$$\lim_{a \to 0} Area = \frac{1}{a}(a) = 1$$



Can you represent u(t) in terms of unit impulse function?

$$u(t) = \int_{-\infty}^{t} \delta(x) dx$$



Another Important Fact about Unit Impulse Function!

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

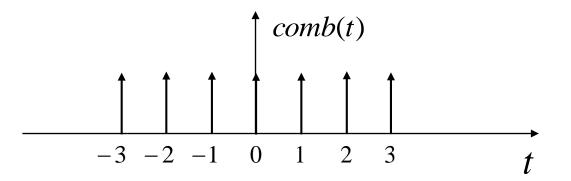
$$\Rightarrow \int_{-\infty}^{\infty} g(t)\delta(t)dt = g(0)$$

Isn't it Sampling?



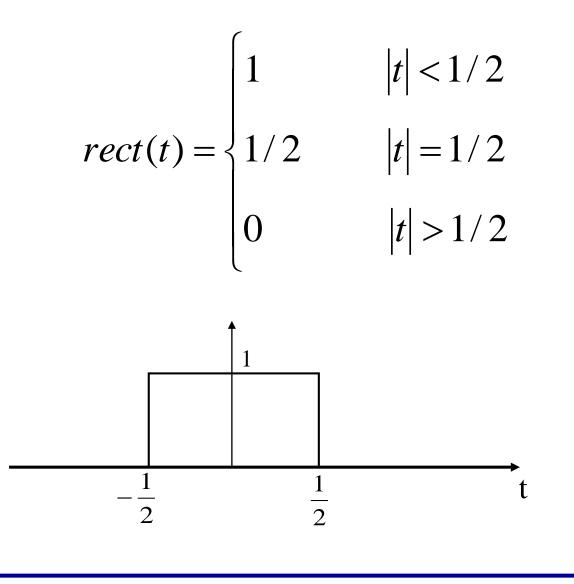
#### **Unit** Comb

$$comb(t) = \sum_{n=-\infty}^{n=\infty} \delta(t-n)$$



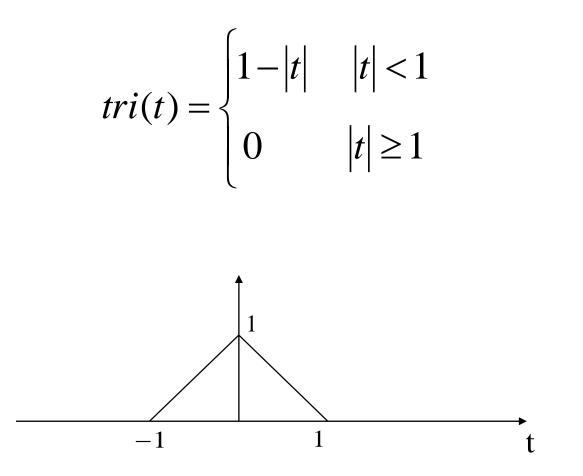


#### **Rectangular Function**





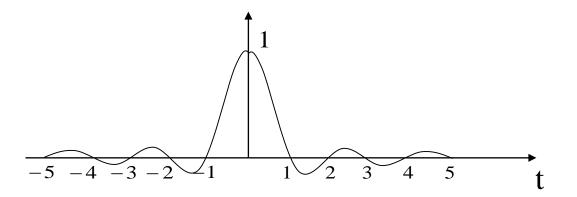
#### **Triangular Function**





#### **Unit Sinc Function**

$$\sin c(t) = \frac{\sin(\pi t)}{\pi t}$$





## **Combinations of Functions**

$$g(t) = \sin c(t) \cos(20\pi t)$$

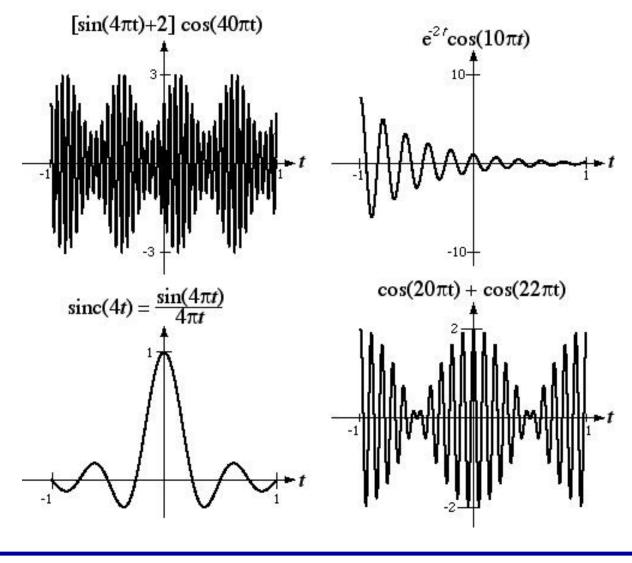
$$g(t) = Ae^{-t}\cos 20\pi t$$

$$g(t) = u(t) + ramp(t)$$

$$g(t) = \operatorname{sgn}(t)\sin(2\pi t)$$



#### Some More Examples





## **Amplitude Transformations of Functions**

Amplitude Shifting

$$g(t) \to A + g(t)$$

Amplitude Scaling

 $g(t) \rightarrow Ag(t)$ 



### **Time Transformations of Functions**

**Time Shifting** 

$$g(t) \to g(t-a)$$

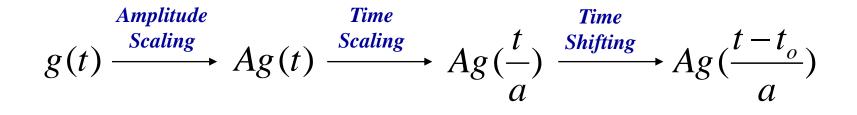
*Time Scaling* 

$$g(t) \rightarrow g(\frac{t}{a})$$



### Multiple Transformations

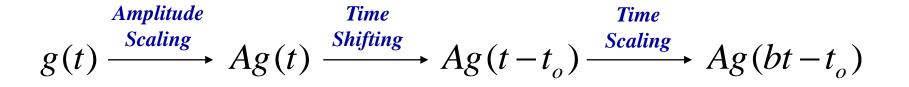
Case 1 
$$g(t) \to Ag(\frac{t-t_o}{a})$$



Case 2

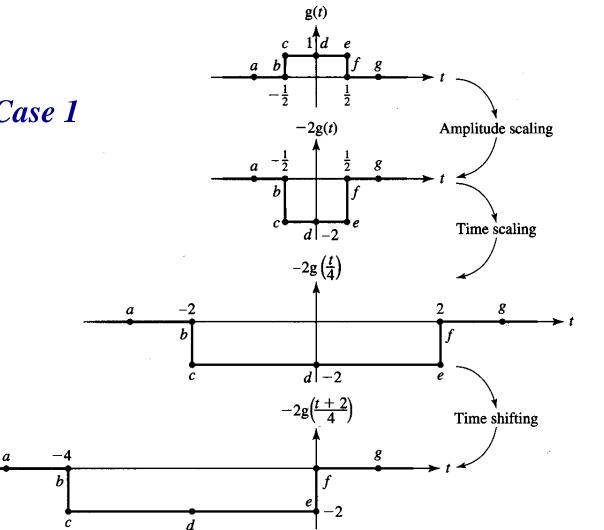
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$$g(t) \to Ag(bt - t_o)$$





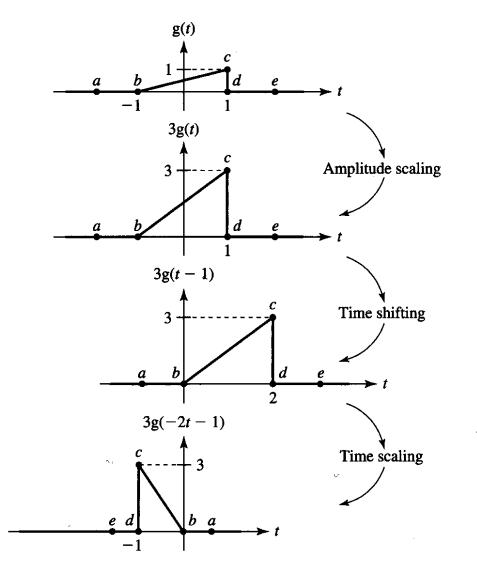


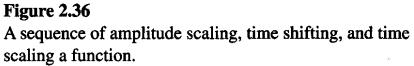




A sequence of amplitude scaling, time scaling, and time shifting a function.







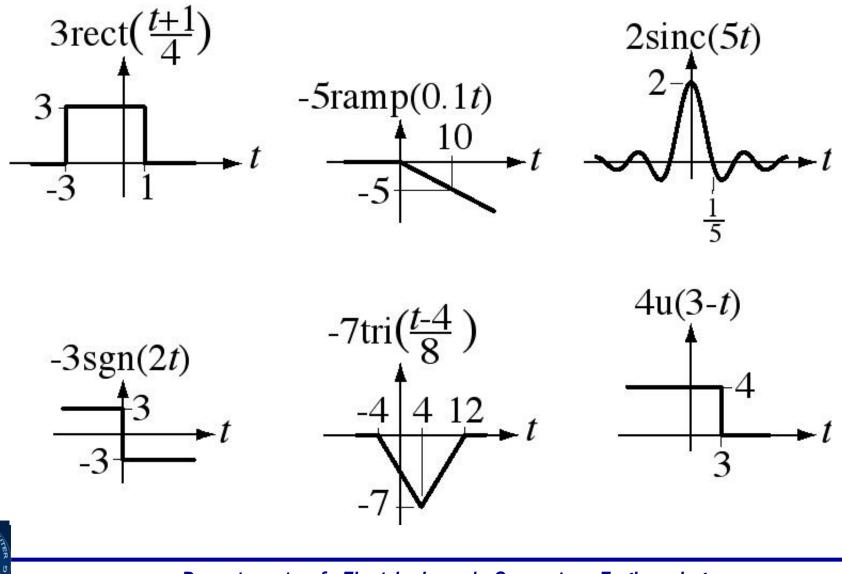
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**Example of Case 2** 

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### Some More Examples



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# **Differentiation and Integration of Functions**

Differentiation:

Slope of the function at time t

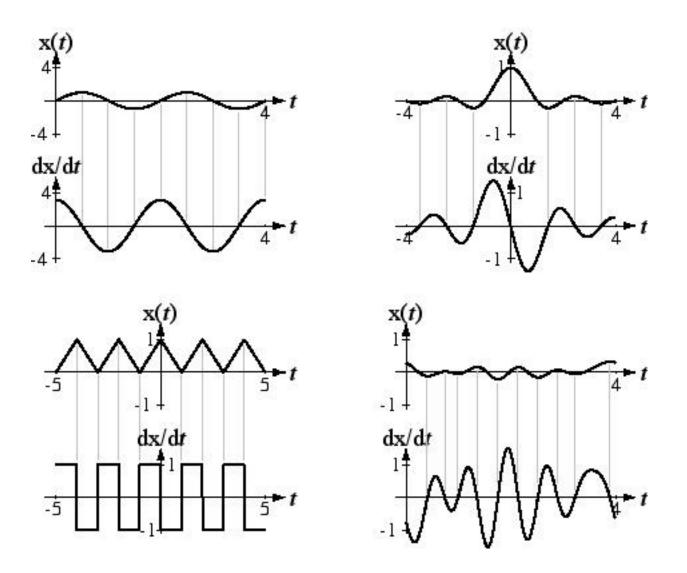
$$\frac{dg(t)}{dt}$$

Integration: Accumulative area under the curve

$$\int_{-\infty}^{t} g(x) dx$$

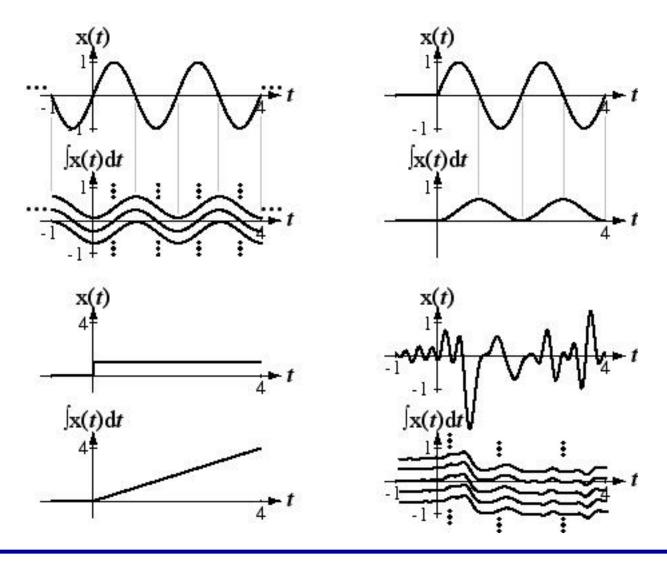


#### **Differentiation** – A kind of Transformation of a Signal





#### Integration – A kind of Transformation of a Signal



### **Even and Odd Functions**

**Function is Even if** g(t) = g(-t)

**Example:**  $\cos(\omega t)$ 

# **Function is Odd if** g(t) = -g(-t)

**Example:**  $sin(\omega t)$ 



### Even and Odd Components of a Function

#### If function is neither even nor odd, then

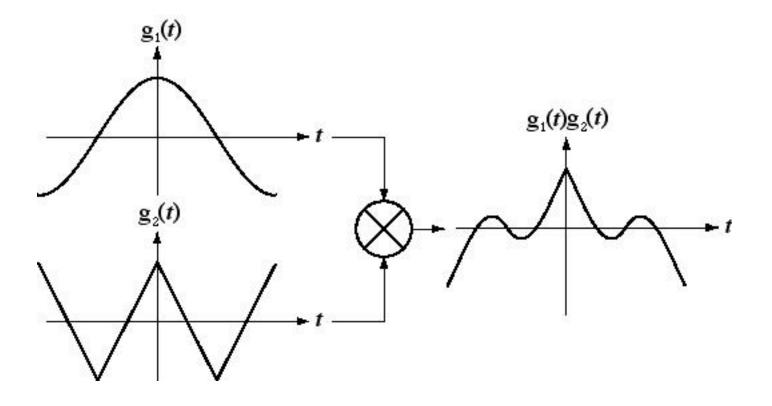
$$g(t) = g_e(t) + g_o(t)$$

Where

$$g_e(t) = \frac{g(t) + g(-t)}{2}$$

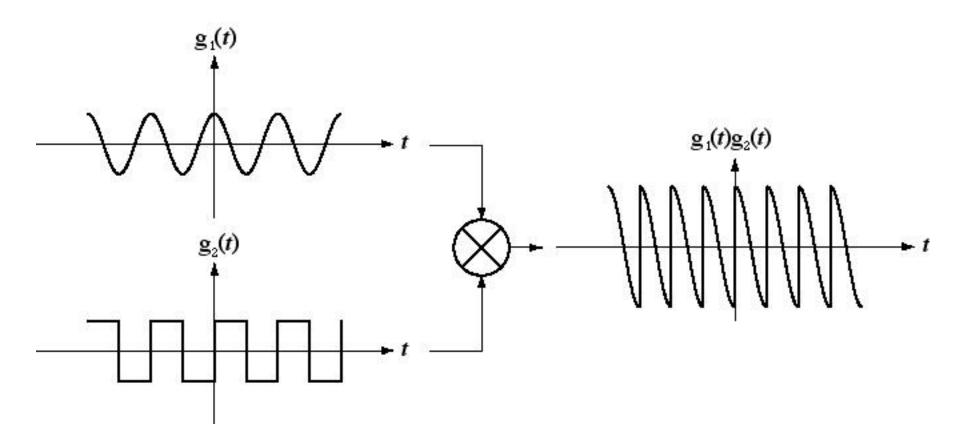
$$g_o(t) = \frac{g(t) - g(-t)}{2}$$





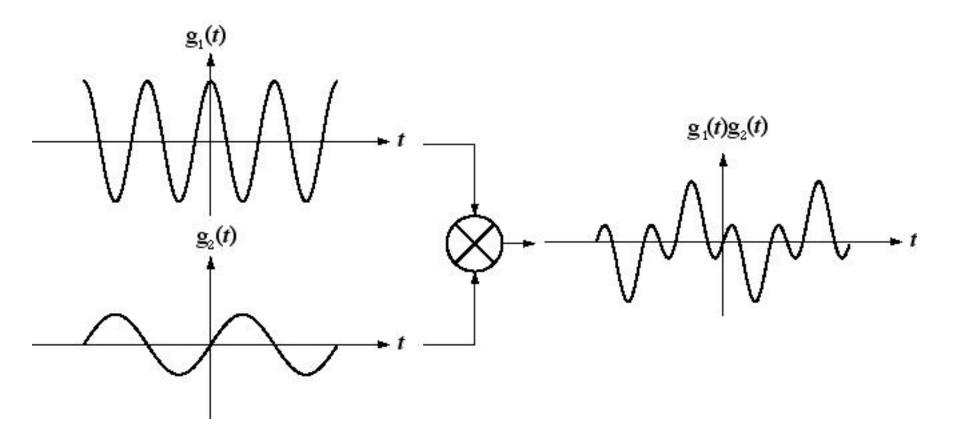
Even x Even = Even





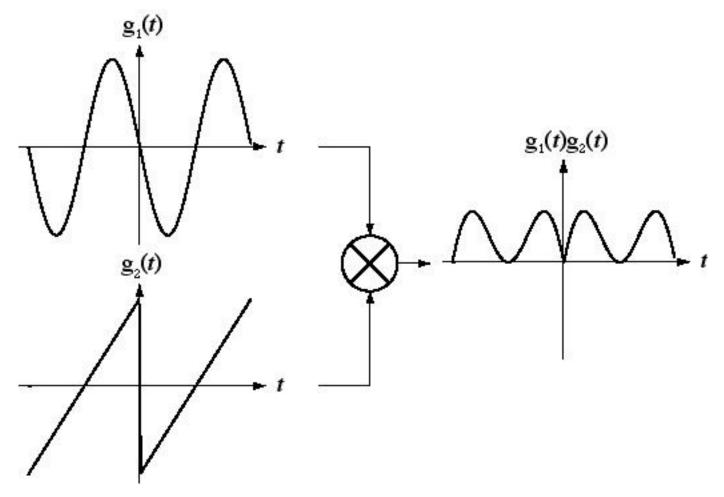
Even x Odd = Odd





Even x Odd = Odd

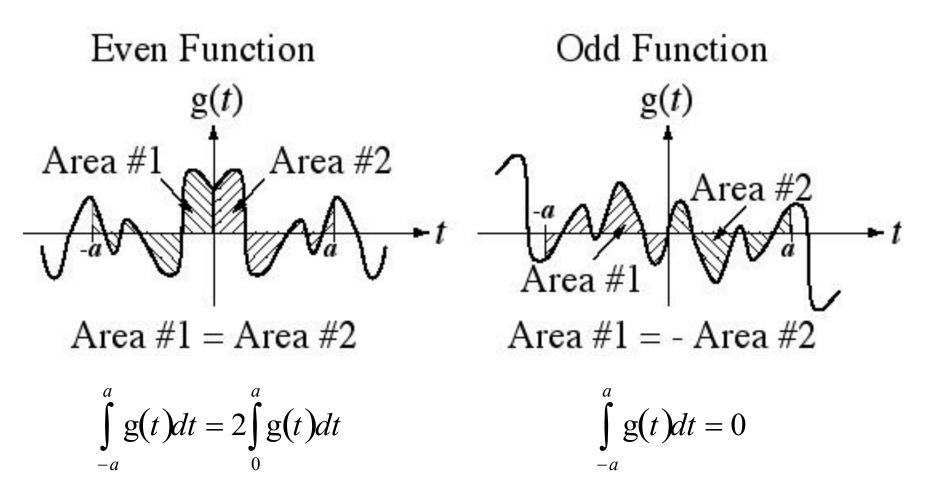




 $Odd \ x \ Odd = Even$ 



# Integrals of Even and Odd CT Functions





### **Continuous Time Periodic Functions**

Function is periodic with period T, if

$$g(t) = g(t + nT)$$

### What is the effect on periodic function of time shifting by nT?



# **Examples of Periodic Signals**

$$g(t) = 3\sin(400\pi t)$$

$$g(t) = 2 + t^2$$

$$g(t) = \sin(12\pi t) + \sin(6\pi t)$$

 $g(t) = \sin(\pi t) + \sin(6\pi t)$ 



### **Discrete Time Signals**

**Continuous Time** 

$$x(t) = A\sin(2\pi f_0 t)$$

#### **Discrete Time**

$$x[nT_s] = A\sin[2\pi f_o nT_s]$$

$$=A\sin[2\pi f_o T_s n]$$

$$=A\sin[\frac{2\pi f_o}{f_s}n]$$



$$x[nT_s] = A\sin[\frac{2\pi f_o}{f_s}n]$$

$$x[n] = A\sin[2\pi \frac{f_o}{f_s}n]$$

$$x[n] = A\sin[2\pi \frac{T_s}{T_o}n]$$

$$x[n] = A\sin[2\pi Kn]$$

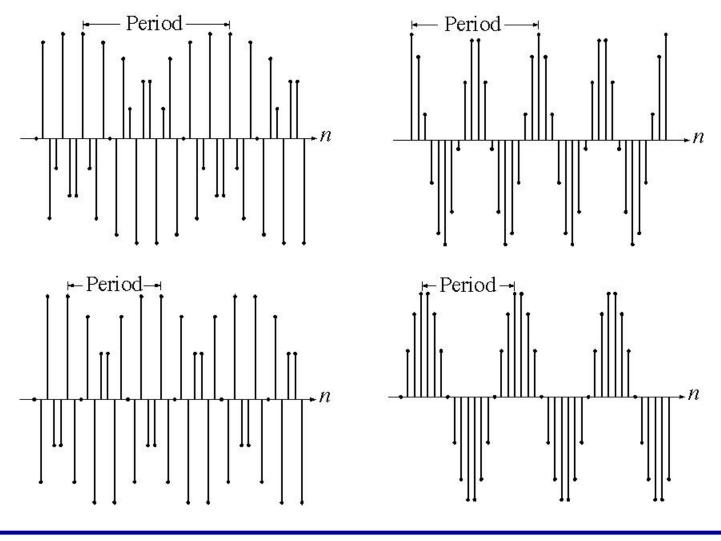
To be periodic, "Kn" has to be an integer for some "n" => K has to be a ratio of integers

$$x[n] = A\sin[2\pi \frac{p}{q}n]$$

Period = q

# **Discrete-Time Sinusoids**

#### **Periodic Sinusoids**



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# How Many CT periodic Cycles are Present in One DT Periodic Cycle

$$x[n] = A \sin[2\pi \frac{p}{q}n]$$
 Period = q

$$x[n] = A\sin[2\pi p\frac{n}{q}]$$

$$x[n] = A \sin[2\pi p] \qquad \qquad \text{When } n = q \\ \text{one DT period}$$

=> There are p cycles of CT periodic sinusoidal function per one cycle of DT periodic sinusoidal function

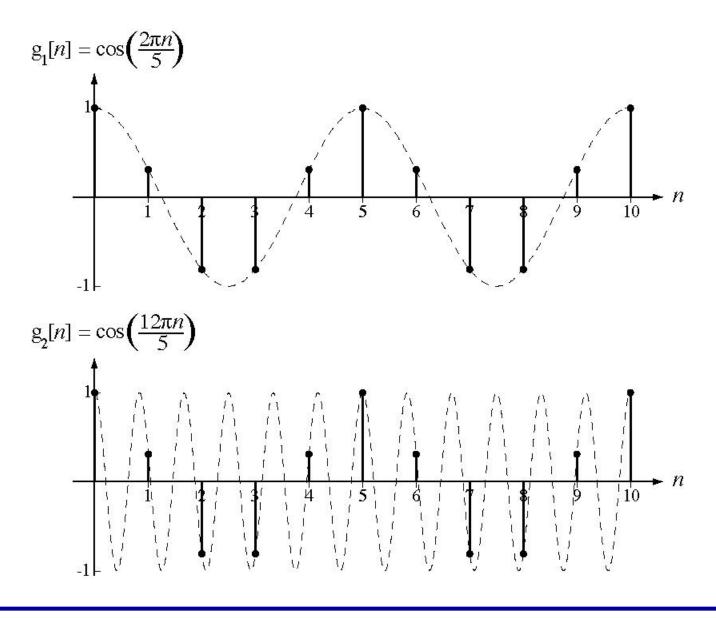
# **Examples**

$$g_1[n] = \cos\left[\frac{2\pi}{5}n\right]$$
 Period = 5

$$g_2[n] = \cos\left[\frac{12\pi}{5}n\right]$$

Period = 5







# Two Discrete Sinusoids could be similar?

Two different-looking DT sinusoids,

 $g_1[n] = A\cos(2\pi K_1 n + \theta)$  and  $g_2[n] = A\cos(2\pi K_2 n + \theta)$ 

may actually be the same. If

 $K_2 = K_1 + m$ , where *m* is an integer

then (because *n* is discrete time and therefore an integer),

$$A\cos(2\pi K_1 n + \theta) = A\cos(2\pi K_2 n + \theta)$$

(Example on next slide)



# **Examples**

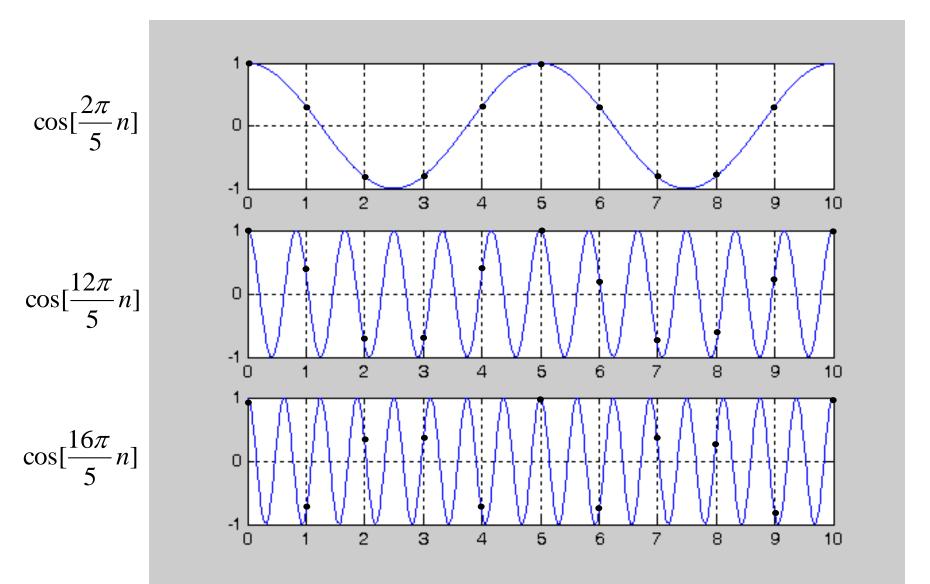
$$g_1[n] = \cos\left[\frac{2\pi}{5}n\right]$$
 Period = 5

$$g_2[n] = \cos\left[\frac{12\pi}{5}n\right]$$

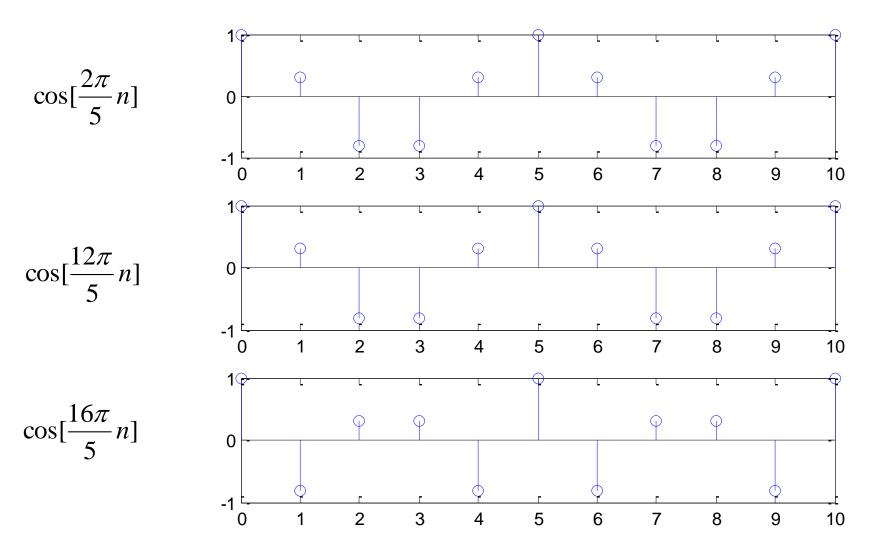
Period = 5

$$g_3[n] = \cos\left[\frac{16\pi}{5}n\right] \qquad Period = 5$$











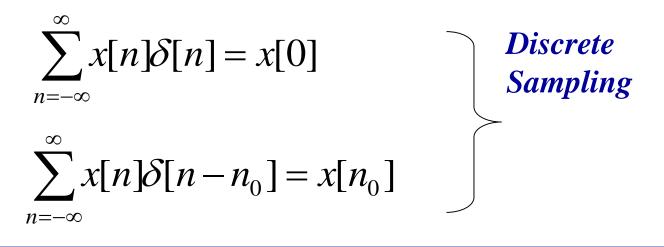
### **Other Discrete Functions**

**Unit Impulse Function** 

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$

Please note:

$$\delta[n] = \delta[an]$$





#### **Unit Step Function**

$$u[n] = \begin{cases} 1 & n \ge 0 \\ 0 & n < 0 \end{cases}$$

**Unit Ramp Function** 

$$ramp[n] = \begin{cases} n & n \ge 0\\ 0 & n < 0 \end{cases}$$



#### **Rectangular Function**

$$rect_{N_{w}}[n] = \begin{cases} 1 & |n| \le N_{w} \\ 0 & |n| > N_{w} \end{cases}$$

#### **Please note that**

$$rect_{N_{w}}[n] = u[n + N_{w}] - u[n - N_{w} - 1]$$



**Transformations on Discrete Time Functions** 

Amplitude Shifting

 $g[n] \rightarrow A + g[n]$ 

Amplitude Scaling

 $g[n] \rightarrow Ag[n]$ 



**Time Shifting** 

$$g[n] \rightarrow g[n-a]$$

Same as continuous time

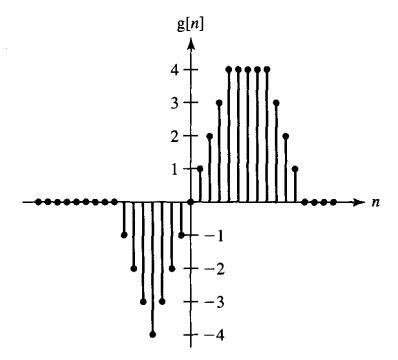
*Time Scaling* 

$$g[n] \rightarrow g[\frac{n}{a}]$$

Tricky! Isn't it?



### **Example of Time Shifting**



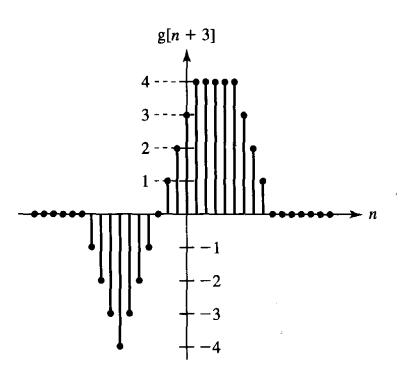
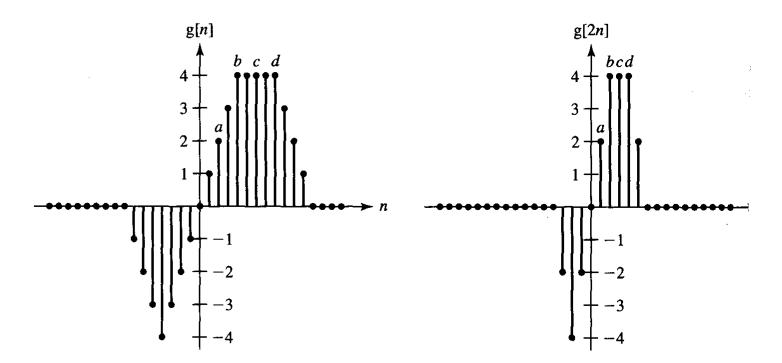


Figure 2.68 Graphical definition of a DT function g[n], where g[n] = 0 and |n| > 15.

Figure 2.69 Graph of g[n + 3] illustrating the time-shifting functional transformation.



#### **Example of Time Compression**



**Figure 2.70** Time compression for a DT function.



**Discrete Time Even and Odd Functions** 

**Function is Even if** g[n] = g[-n]

**Function is Odd if** g[n] = -g[-n]

If function is neither even nor odd, then

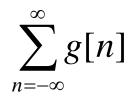
$$g[n] = g_e[n] + g_o[n]$$

Where 
$$g_e[n] = \frac{g[n] + g[-n]}{2}$$

$$g_o[n] = \frac{g[n] - g[-n]}{2}$$

# **Differencing and Accumulation**

# $\Delta g[n] = g[n+1] - g[n]$





### Energy of a Signal

For Continuous Time Signals

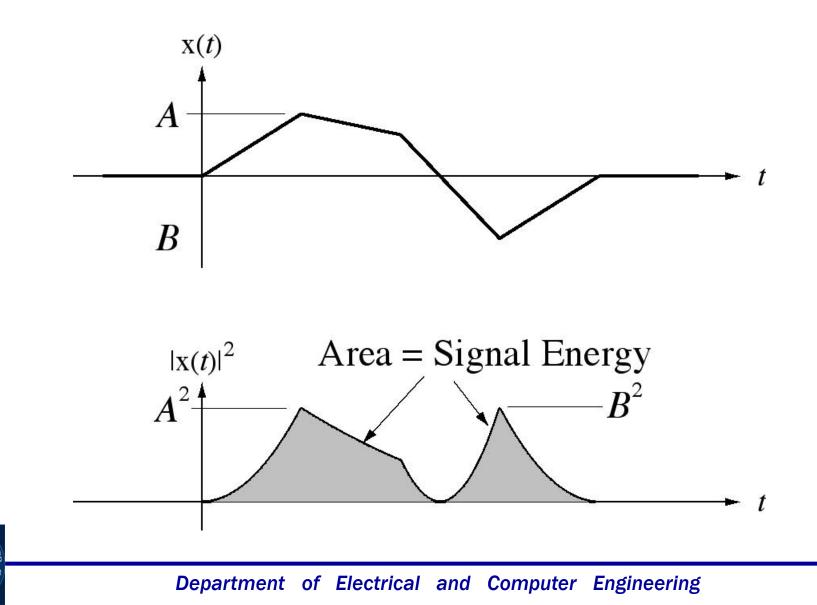
$$E_x = \int_{-\infty}^{\infty} \left| x(t) \right|^2 dt$$

For Discrete Time Signals

$$E_x = \sum_{n=-\infty}^{\infty} \left| x[n] \right|^2$$

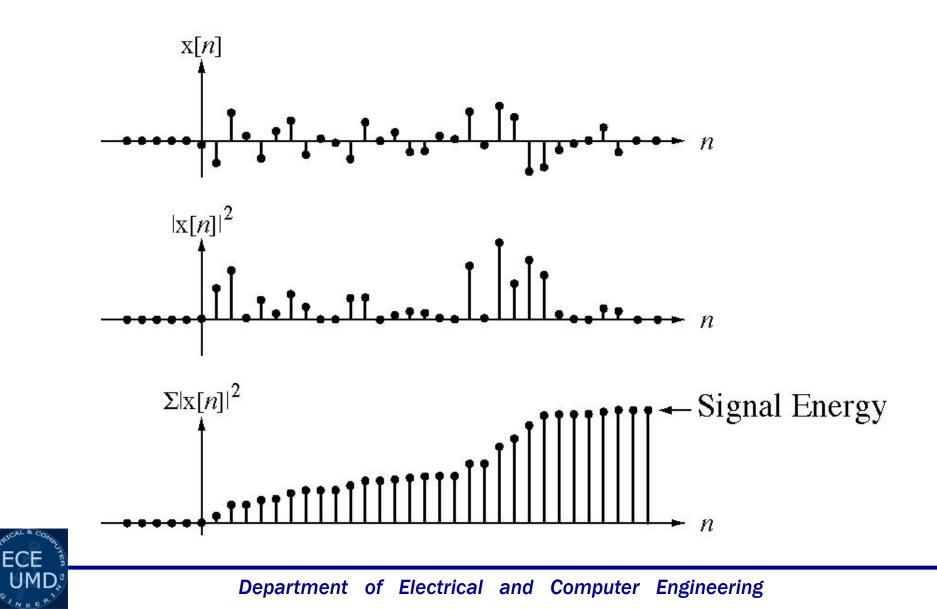


# Visual Example of Energy of a Signal – CT Signal



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### Visual Example of Energy of a Signal – DT Signal



### Power of a Signal

Some signals have infinite signal energy. In that case It is more convenient to deal with average signal power.

For Continuous Time Signals

$$P_{x} = \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^{2} dt$$

For Discrete Time Signals

$$P_{x} = \lim_{N \to \infty} \frac{1}{2N} \sum_{n=-N}^{N-1} |x[n]|^{2}$$



# Power of a Periodic Signal

For a periodic CT signal, x(t), the average signal power is

$$P_x = \frac{1}{T} \int_T |\mathbf{x}(t)|^2 dt$$

where T is any period of the signal.

For a periodic DT signal, x[n], the average signal power is

$$P_x = \frac{1}{N} \sum_{n = \langle N \rangle} |\mathbf{x}[n]^2$$

where N is any period of the signal.



# **Energy and Power Signals**

A signal with finite signal energy is called an **energy signal**.

A signal with infinite signal energy and finite average signal energy is called a **power signal.** 

