

1.  $y_c(x) = c_1 + c_2x, y_p(x) = \frac{x^2}{2}$
2.  $y_p(x) = \frac{1}{4}e^{2x}$
3.  $y(x) = c_1e^{4x} + c_2e^{-4x} + c_3xe^{-4x} + c_4 \cos(2x) + c_5 \sin(2x)$
4.  $D^2 + 9$
5.  $y_p(t) = Ate^{2t}$
6.  $G(s) = 3\frac{1}{(s-2)^2} - \frac{e^{-4s}}{s}$
7. proof in book, Example 2, p. 577
8.  $f(t) = 3 + u(t-3)(t^2 - 3) + u(t-4)(\cos(t) - t^2)$
9.  $y(t) = 2e^{4t}$
10.  $Y(s) = \frac{3s+3(s^2+16)}{(s^2+16)(s^2+s+2)}$
11.  $f(t) = \frac{17}{7}e^{-4t} + \frac{4}{7}e^{3t}$
12. Let  $v = y'$ . Then  $v' = 6v + 2y + \cos(2t)$ . Vector form:  $\vec{x}' = \begin{bmatrix} 0 & 1 \\ 2 & 6 \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ \cos(2t) \end{bmatrix}$ , where  $\vec{x} = \begin{bmatrix} y \\ v \end{bmatrix}$ .
13. (a) Need to verify:  $A\vec{v} = \lambda\vec{v}$ :  $\begin{bmatrix} 1 & 2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$ , and  $2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$ . These are equal, so it is verified.  
 (b)  $\vec{x}(t) = c_1e^{2t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2e^{-3t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$   
 (c)  $\vec{x}(t) = 2e^{2t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 1e^{-3t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$
14. Eigenvalues/eigenvectors:  $i, \begin{bmatrix} i \\ 1 \end{bmatrix}$ , or  $-i, \begin{bmatrix} -i \\ 1 \end{bmatrix}$   
 Solution:  $\vec{x}(t) = c_1e^{-3t} \begin{bmatrix} 4 \\ 1 \end{bmatrix} + c_2e^{2t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  (or equivalent)
15. (a) Any one of  $(0, 0)$ ,  $(2, 0)$ , or  $(1, 1)$   
 (b) Vector from  $(2, 1)$  is  $(-2, 1)$ ; vector from  $(1, 1/2)$  is  $(1/2, 0)$
16. (Extra Credit) In book, middle of p. 588