

# Concurrency Control

## Chapter 17

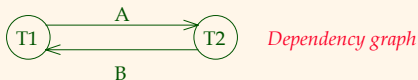
# Conflict Serializable Schedules

- ❖ Two schedules are **conflict equivalent** if:
  - Involve the same actions of the same transactions
  - Every pair of conflicting actions is ordered the same way
- ❖ Schedule S is **conflict serializable** if S is conflict equivalent to some serial schedule

# Example

- ❖ A schedule that is not conflict serializable:

T1:	R(A), W(A),	R(B), W(B)
T2:	R(A), W(A), R(B), W(B)	



- ❖ The cycle in the graph reveals the problem. The output of T1 depends on T2, and vice-versa.

# Dependency Graph

- ❖ **Dependency graph**: One node per Xact; edge from  $T_i$  to  $T_j$  if  $T_j$  reads/writes an object last written by  $T_i$ .
- ❖ **Theorem**: Schedule is conflict serializable if and only if its dependency graph is acyclic

# Review: Strict 2PL

- ❖ **Strict Two-phase Locking (Strict 2PL) Protocol**:
  - Each Xact must obtain a **S (shared) lock** on object before reading, and an **X (exclusive) lock** on object before writing.
  - All locks held by a transaction are released when the transaction completes
  - If an Xact holds an X lock on an object, no other Xact can get a lock (S or X) on that object.
- ❖ Strict 2PL allows only schedules whose precedence graph is acyclic

# Two-Phase Locking (2PL)

- ❖ **Two-Phase Locking Protocol**
  - Each Xact must obtain a **S (shared) lock** on object before reading, and an **X (exclusive) lock** on object before writing.
  - **A transaction can not request additional locks once it releases any locks.**
  - If an Xact holds an X lock on an object, no other Xact can get a lock (S or X) on that object.

## View Serializability

- ❖ Schedules S1 and S2 are **view equivalent** if:
  - If  $T_i$  reads initial value of A in S1, then  $T_i$  also reads initial value of A in S2
  - If  $T_i$  reads value of A written by  $T_j$  in S1, then  $T_i$  also reads value of A written by  $T_j$  in S2
  - If  $T_i$  writes final value of A in S1, then  $T_i$  also writes final value of A in S2

T1: R(A)	W(A)	T1: R(A),W(A)
T2: W(A)		T2: W(A)
T3: W(A)		T3: W(A)

## Lock Management

- ❖ Lock and unlock requests are handled by the lock manager
- ❖ Lock table entry:
  - Number of transactions currently holding a lock
  - Type of lock held (shared or exclusive)
  - Pointer to queue of lock requests
- ❖ Locking and unlocking have to be atomic operations
- ❖ Lock upgrade: transaction that holds a shared lock can be upgraded to hold an exclusive lock

## Deadlocks

- ❖ **Deadlock**: Cycle of transactions waiting for locks to be released by each other.
- ❖ Two ways of dealing with deadlocks:
  - Deadlock prevention
  - Deadlock detection

## Deadlock Prevention

- ❖ Assign priorities based on timestamps. Assume  $T_i$  wants a lock that  $T_j$  holds. Two policies are possible:
  - Wait-Die: If  $T_i$  has higher priority,  $T_i$  waits for  $T_j$ ; otherwise  $T_i$  aborts
  - Wound-wait: If  $T_i$  has higher priority,  $T_j$  aborts; otherwise  $T_i$  waits
- ❖ If a transaction re-starts, make sure it has its original timestamp

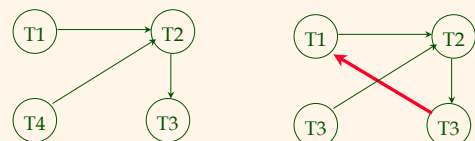
## Deadlock Detection

- ❖ Create a **waits-for graph**:
  - Nodes are transactions
  - There is an edge from  $T_i$  to  $T_j$  if  $T_i$  is waiting for  $T_j$  to release a lock
- ❖ Periodically check for cycles in the waits-for graph

## Deadlock Detection (Continued)

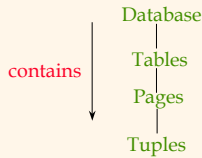
Example:

T1: S(A), R(A), S(B)  
 T2: X(B), W(B)  
 T3: S(C), R(C)  
 T4: X(C), X(A)



## Multiple-Granularity Locks

- ❖ Hard to decide what granularity to lock (tuples vs. pages vs. tables).
- ❖ Shouldn't have to decide!
- ❖ Data "containers" are nested:



## Solution: New Lock Modes, Protocol

- ❖ Allow Xacts to lock at each level, but with a special protocol using new "intention" locks:
- ❖ Before locking an item, Xact must set "intention locks" on all its ancestors.
- ❖ For unlock, go from specific to general (i.e., bottom-up).
- ❖ **SIX mode**: Like S & IX at the same time.

	--	IS	IX	S	X
--	✓	✓	✓	✓	✓
IS	✓	✓	✓	✓	
IX	✓	✓	✓		
S	✓	✓		✓	
X	✓				

## Multiple Granularity Lock Protocol

- ❖ Each Xact starts from the root of the hierarchy.
- ❖ To get S or IS lock on a node, must hold IS or IX on parent node.
  - What if Xact holds SIX on parent? S on parent?
- ❖ To get X or IX or SIX on a node, must hold IX or SIX on parent node.
- ❖ Must release locks in bottom-up order.

Protocol is correct in that it is equivalent to directly setting locks at the leaf levels of the hierarchy.

## Examples

- ❖ T1 scans R, and updates a few tuples:
  - T1 gets an SIX lock on R, then repeatedly gets an S lock on tuples of R, and occasionally upgrades to X on the tuples.
- ❖ T2 uses an index to read only part of R:
  - T2 gets an IS lock on R, and repeatedly gets an S lock on tuples of R.
- ❖ T3 reads all of R:
  - T3 gets an S lock on R.
  - OR, T3 could behave like T2; can use **lock escalation** to decide which.

	--	IS	IX	S	X
--	✓	✓	✓	✓	✓
IS	✓	✓	✓	✓	
IX	✓	✓	✓		
S	✓	✓		✓	
X	✓				

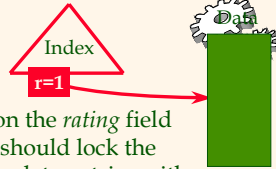
## Dynamic Databases

- ❖ If we relax the assumption that the DB is a fixed collection of objects, even Strict 2PL will not assure serializability:
  - T1 locks all pages containing sailor records with *rating* = 1, and finds **oldest** sailor (say, *age* = 71).
  - Next, T2 inserts a new sailor; *rating* = 1, *age* = 96.
  - T2 also deletes oldest sailor with *rating* = 2 (and, say, *age* = 80), and commits.
  - T1 now locks all pages containing sailor records with *rating* = 2, and finds **oldest** (say, *age* = 63).
- ❖ No consistent DB state where T1 is "correct"!

## The Problem

- ❖ T1 implicitly assumes that it has locked the set of all sailor records with *rating* = 1.
  - Assumption only holds if no sailor records are added while T1 is executing!
  - Need some mechanism to enforce this assumption. (**Index locking and predicate locking**.)
- ❖ Example shows that conflict serializability guarantees serializability only if the set of objects is fixed!

## Index Locking



- ❖ If there is a dense index on the *rating* field using Alternative (2), T1 should lock the index page containing the data entries with *rating* = 1.
  - If there are no records with *rating* = 1, T1 must lock the index page where such a data entry *would* be, if it existed!
- ❖ If there is no suitable index, T1 must lock all pages, and lock the file/table to prevent new pages from being added, to ensure that no new records with *rating* = 1 are added.

## Predicate Locking

- ❖ Grant lock on all records that satisfy some logical predicate, e.g. *age* > 2\**salary*.
- ❖ Index locking is a special case of predicate locking for which an index supports efficient implementation of the predicate lock.
  - What is the predicate in the sailor example?
- ❖ In general, predicate locking has a lot of locking overhead.

## Locking in B+ Trees

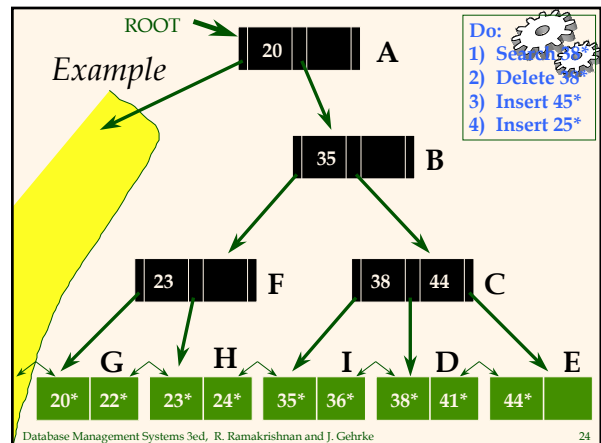
- ❖ How can we efficiently lock a particular leaf node?
  - Btw, don't confuse this with multiple granularity locking!
- ❖ One solution: Ignore the tree structure, just lock pages while traversing the tree, following 2PL.
- ❖ This has terrible performance!
  - Root node (and many higher level nodes) become bottlenecks because every tree access begins at the root.

## Two Useful Observations

- ❖ Higher levels of the tree only direct searches for leaf pages.
- ❖ For inserts, a node on a path from root to modified leaf must be locked (in X mode, of course), only if a split can propagate up to it from the modified leaf. (Similar point holds w.r.t. deletes.)
- ❖ We can exploit these observations to design efficient locking protocols that guarantee serializability *even though they violate 2PL*.

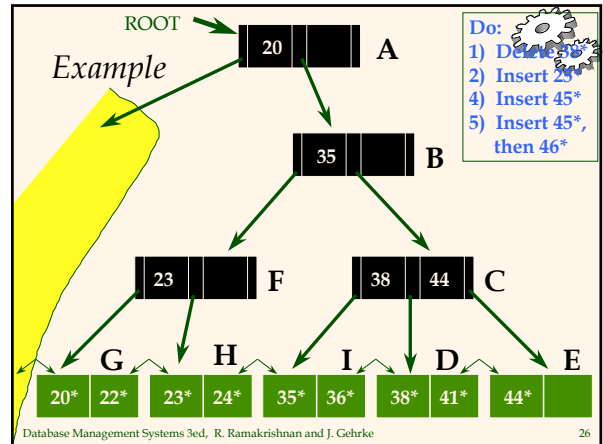
## A Simple Tree Locking Algorithm

- ❖ **Search:** Start at root and go down; repeatedly, S lock child then unlock parent.
- ❖ **Insert/Delete:** Start at root and go down, obtaining X locks as needed. Once child is locked, check if it is **safe**:
  - If child is safe, release all locks on ancestors.
- ❖ **Safe node:** Node such that changes will not propagate up beyond this node.
  - Inserts: Node is not full.
  - Deletes: Node is not half-empty.



## A Better Tree Locking Algorithm (See Bayer-Scholnick paper)

- ❖ **Search:** As before.
- ❖ **Insert/Delete:**
  - Set locks as if for search, get to leaf, and set X lock on leaf.
  - If leaf is not **safe**, release all locks, and restart Xact using previous Insert/Delete protocol.
- ❖ Gambles that only leaf node will be modified; if not, S locks set on the first pass to leaf are wasteful. In practice, better than previous alg.



## Even Better Algorithm

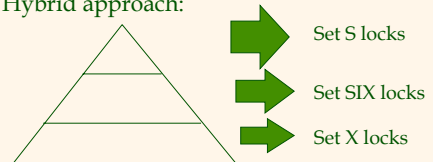
- ❖ **Search:** As before.
- ❖ **Insert/Delete:**
  - Use original Insert/Delete protocol, but set IX locks instead of X locks at all nodes.
  - Once leaf is locked, convert all IX locks to X locks **top-down**: i.e., starting from node nearest to root. (Top-down reduces chances of deadlock.)

(Contrast use of IX locks here with their use in multiple-granularity locking.)

## Hybrid Algorithm

- ❖ The likelihood that we really need an X lock decreases as we move up the tree.

- ❖ Hybrid approach:

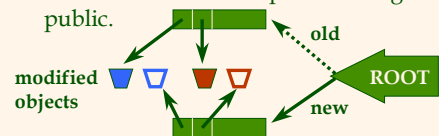


## Optimistic CC (Kung-Robinson)

- ❖ Locking is a conservative approach in which conflicts are prevented. Disadvantages:
  - Lock management overhead.
  - Deadlock detection/resolution.
  - Lock contention for heavily used objects.
- ❖ If conflicts are rare, we might be able to gain concurrency by not locking, and instead checking for conflicts before Xacts commit.

## Kung-Robinson Model

- ❖ Xacts have three phases:
  - **READ:** Xacts read from the database, but make changes to private copies of objects.
  - **VALIDATE:** Check for conflicts.
  - **WRITE:** Make local copies of changes public.



## Validation

- ❖ Test conditions that are **sufficient** to ensure that no conflict occurred.
- ❖ Each Xact is assigned a numeric id.
  - Just use a **timestamp**.
- ❖ Xact ids assigned at end of READ phase, just before validation begins. (Why then?)
- ❖ **ReadSet(Ti)**: Set of objects read by Xact Ti.
- ❖ **WriteSet(Ti)**: Set of objects modified by Ti.

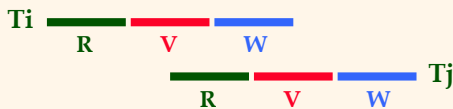
## Test 1

- ❖ For all i and j such that  $T_i < T_j$ , check that  $T_i$  completes before  $T_j$  begins.



## Test 2

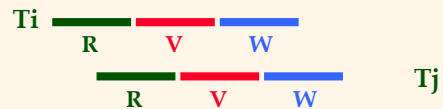
- ❖ For all i and j such that  $T_i < T_j$ , check that:
  - $T_i$  completes before  $T_j$  begins its Write phase +
  - $WriteSet(T_i) \cap ReadSet(T_j)$  is empty.



Does  $T_j$  read dirty data? Does  $T_i$  overwrite  $T_j$ 's writes?

## Test 3

- ❖ For all i and j such that  $T_i < T_j$ , check that:
  - $T_i$  completes Read phase before  $T_j$  does +
  - $WriteSet(T_i) \cap ReadSet(T_j)$  is empty +
  - $WriteSet(T_i) \cap WriteSet(T_j)$  is empty.



Does  $T_j$  read dirty data? Does  $T_i$  overwrite  $T_j$ 's writes?

## Applying Tests 1 & 2: Serial Validation

- ❖ To validate Xact T:

```

valid = true;
// S = set of Xacts that committed after Begin(T)
< foreach Ts in S do {
  if ReadSet(Ts) does not intersect WriteSet(Ts)
    then valid = false;
}
if valid then { install updates; // Write phase
  Commit T } >
else Restart T
    
```

end of critical section

## Comments on Serial Validation

- ❖ Applies Test 2, with T playing the role of  $T_j$  and each Xact in  $T_s$  (in turn) being  $T_i$ .
- ❖ Assignment of Xact id, validation, and the Write phase are inside a **critical section!**
  - I.e., Nothing else goes on concurrently.
  - If Write phase is long, major drawback.
- ❖ Optimization for Read-only Xacts:
  - Don't need critical section (because there is no Write phase).

## Serial Validation (Contd.)

- ❖ **Multistage serial validation:** Validate in stages, at each stage validating T against a subset of the Xacts that committed after Begin(T).
  - Only last stage has to be inside critical section.
- ❖ **Starvation:** Run starving Xact in a critical section (!!)
- ❖ **Space for WriteSets:** To validate Tj, must have WriteSets for all Ti where  $T_i < T_j$  and Ti was active when Tj began. There may be many such Xacts, and we may run out of space.
  - Tj's validation fails if it requires a missing WriteSet.
  - No problem if Xact ids assigned at start of Read phase.

## Overheads in Optimistic CC

- ❖ Must record read/write activity in ReadSet and WriteSet per Xact.
  - Must create and destroy these sets as needed.
- ❖ Must check for conflicts during validation, and must make validated writes "global".
  - Critical section can reduce concurrency.
  - Scheme for making writes global can reduce clustering of objects.
- ❖ Optimistic CC restarts Xacts that fail validation.
  - Work done so far is wasted; requires clean-up.

## "Optimistic" 2PL

- ❖ If desired, we can do the following:
  - Set S locks as usual.
  - Make changes to private copies of objects.
  - Obtain all X locks at end of Xact, make writes global, then release all locks.
- ❖ In contrast to Optimistic CC as in Kung-Robinson, this scheme results in Xacts being blocked, waiting for locks.
  - However, no validation phase, no restarts (modulo deadlocks).

## Timestamp CC

- ❖ **Idea:** Give each object a read-timestamp (RTS) and a write-timestamp (WTS), give each Xact a timestamp (TS) when it begins:
  - If action ai of Xact Ti conflicts with action aj of Xact Tj, and  $TS(T_i) < TS(T_j)$ , then ai must occur before aj. Otherwise, restart violating Xact.

## When Xact T wants to read Object O

- ❖ If  $TS(T) < WTS(O)$ , this violates timestamp order of T w.r.t. writer of O.
  - So, abort T and restart it with a new, larger TS. (If restarted with same TS, T will fail again! Contrast use of timestamps in 2PL for ddk prevention.)
- ❖ If  $TS(T) > WTS(O)$ :
  - Allow T to read O.
  - Reset  $RTS(O)$  to  $\max(RTS(O), TS(T))$
- ❖ Change to  $RTS(O)$  on reads must be written to disk! This and restarts represent overheads.

## When Xact T wants to Write Object O

- ❖ If  $TS(T) < RTS(O)$ , this violates timestamp order of T w.r.t. writer of O; abort and restart T.
- ❖ If  $TS(T) < WTS(O)$ , violates timestamp order of T w.r.t. writer of O.
  - **Thomas Write Rule:** We can safely ignore such outdated writes; need not restart T! (T's write is effectively followed by another write, with no intervening reads.) Allows some serializable but non conflict serializable schedules:
- ❖ Else, allow T to write O.

T1	T2
R(A)	
	W(A) Commit
W(A) Commit	

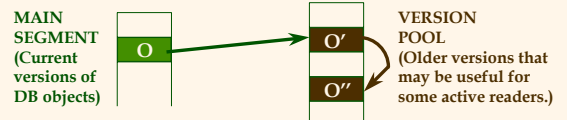
## Timestamp CC and Recoverability

- ❖ Unfortunately, unrecoverable schedules are allowed:
- ❖ Timestamp CC can be modified to allow only recoverable schedules:
  - Buffer all writes until writer commits (but update  $WTS(O)$  when the write is allowed.)
  - Block readers T (where  $TS(T) > WTS(O)$ ) until writer of O commits.
- ❖ Similar to writers holding X locks until commit, but still not quite 2PL.

T1	T2
W(A)	R(A)
	W(B)
	Commit

## Multiversion Timestamp CC

- ❖ **Idea:** Let writers make a “new” copy while readers use an appropriate “old” copy:

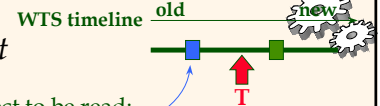


- ❖ Readers are always allowed to proceed.
  - But may be blocked until writer commits.

## Multiversion CC (Contd.)

- ❖ Each version of an object has its writer's TS as its **WTS**, and the TS of the Xact that most recently read this version as its **RTS**.
- ❖ Versions are chained backward; we can discard versions that are “too old to be of interest”.
- ❖ Each Xact is classified as **Reader** or **Writer**.
  - Writer *may* write some object; Reader never will.
  - Xact declares whether it is a Reader when it begins.

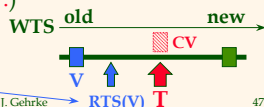
## Reader Xact



- ❖ For each object to be read:
  - Finds **newest version** with  $WTS < TS(T)$ . (Starts with current version in the main segment and chains backward through earlier versions.)
- ❖ Assuming that some version of every object exists from the beginning of time, **Reader Xacts are never restarted**.
  - However, might block until writer of the appropriate version commits.

## Writer Xact

- ❖ To read an object, follows reader protocol.
- ❖ To write an object:
  - Finds **newest version V** s.t.  $WTS < TS(T)$ .
  - If  $RTS(V) < TS(T)$ , T makes a copy **CV** of V, with a pointer to V, with  $WTS(CV) = TS(T)$ ,  $RTS(CV) = TS(T)$ . (Write is buffered until T commits; other Xacts can see TS values but can't read version **CV**.)
  - Else, reject write.



## Transaction Support in SQL-92

- ❖ Each transaction has an access mode, a diagnostics size, and an isolation level.

Isolation Level	Dirty Read	Unrepeatable Read	Phantom Problem
Read Uncommitted	Maybe	Maybe	Maybe
Read Committed	No	Maybe	Maybe
Repeatable Reads	No	No	Maybe
Serializable	No	No	No



## Summary



- ❖ There are several lock-based concurrency control schemes (Strict 2PL, 2PL). Conflicts between transactions can be detected in the dependency graph
- ❖ The lock manager keeps track of the locks issued. Deadlocks can either be prevented or detected.
- ❖ Naïve locking strategies may have the phantom problem

## Summary (Contd.)



- ❖ Index locking is common, and affects performance significantly.
  - Needed when accessing records via index.
  - Needed for **locking logical sets of records** (index locking/predicate locking).
- ❖ Tree-structured indexes:
  - Straightforward use of 2PL very inefficient.
  - Bayer-Schkolnick illustrates potential for improvement.
- ❖ In practice, better techniques now known; do record-level, rather than page-level locking.

## Summary (Contd.)



- ❖ Multiple granularity locking reduces the overhead involved in setting locks for nested collections of objects (e.g., a file of pages); should not be confused with tree index locking!
- ❖ Optimistic CC aims to minimize CC overheads in an "optimistic" environment where reads are common and writes are rare.
- ❖ Optimistic CC has its own overheads however; most real systems use locking.
- ❖ SQL-92 provides different isolation levels that control the degree of concurrency

## Summary (Contd.)



- ❖ Timestamp CC is another alternative to 2PL; allows some serializable schedules that 2PL does not (although converse is also true).
- ❖ Ensuring recoverability with Timestamp CC requires ability to block Xacts, which is similar to locking.
- ❖ Multiversion Timestamp CC is a variant which ensures that read-only Xacts are never restarted; they can always read a suitable older version. Additional overhead of version maintenance.