#### A Study of Two Sampling Methods for Analyzing Large Datasets With ILP

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> Presented by Anand Sivaraman (04/23/2003)

















- 6. Score each clause in  $S_D.$  Let h be the highest score and BestSet be the clauses with score h in  $S_D$
- 7. If h > bestscore and  $\exists Best \in BestSet s.t. B \cup H \cup \{Best\} \not\models \Box, B \cup H \cup \{Best\} \cup E \neg \not\models \Box$ , and  $B \cup H \cup \{Best\} \cup I \not\models \Box$  then bestscore = h and C = Best
- 8. Add each clause in  $S_D$  to O. Sort O according to descending score of clauses
- 9. Go to Step 2







#### A Comparison of Time Complexities

| Problem            | E     | Select   | Refine   | Score     | Sort     |
|--------------------|-------|----------|----------|-----------|----------|
| Trains [19]        | 10    | $10^{0}$ | $10^{1}$ | $10^{2}$  | $10^3$   |
| Pharmacophore [27] | 28    | $10^{0}$ | $10^{2}$ | $10^{3}$  | $10^3$   |
| Mutagenesis [35]   | 188   | $10^{0}$ | $10^{2}$ | $10^{5}$  | $10^4$   |
| Mesh [7]           | 2500  | $10^{0}$ | $10^{2}$ | $10^{7}$  | $10^{4}$ |
| Tagging [5]        | 6000  | $10^{0}$ | $10^{1}$ | $10^{12}$ | $10^2$   |
| KRK [28]           | 10000 | $10^{0}$ | $10^{3}$ | $10^{6}$  | $10^2$   |

Figure 3. A comparison of time-complexities for search steps. The tabulations are based on the following values. Trains: N = 10, a = 1, b = 4, c = 4, d = 1; Pharmacophores N = 10, a = 2, b = 7, c = 4, d = 1; Maganesiss N = 25, a = 2, b = 25, c = 4, d = 1; Mesh: N = 30, a = 1, b = 20, c = 4, d = 1; Magsing: N = 5, a = 1, b = 7, c = 5, d = 5; and KRK: N = 12, a = 6, b = 22, c = 3, d = 1.









 Constructs theories incrementally by sampling from a large pool of data

- Theory revision
  - generalize a set of clauses using sample data
  - Specialize them to maintain consistency with large data pool
  - Revision addition / deletion of clauses
- Possible to determine, and eliminate those clauses responsible for errors
- Hence, only partial reconstruction needed

#### 

the search procedure



#### 15. Go to Step 3



## Bounds on Examples Processed Assume sampling procedure returns no more than m errors each of false positives and false negatives Best case: First sample of 2m errors is sufficient to construct an explanation for E = E<sup>+</sup> U E<sup>-</sup>

Worst case: All examples needed to construct adequate explanation

- · Clauses constructed in every iteration save the last is over general
- Function generalize called with 2m,4m,..examples
- Assume without loss of generality |E<sup>-</sup>| ≥ |E<sup>+</sup>| and n= |E<sup>-</sup>| / |E<sup>+</sup>|
- Then,total examples processed is composed of

Sequence 2m,4m,...2  $|E^+|$  (at the end of which there are no false negatives) And 2  $|E^+|+m,...|E^+|+|E|$  (at the end of which there are no false positives)

- Sum of examples M = |E|/2m ((4n-2n<sup>2</sup>-1) |E|+m)
- Hence, number of examples N processed satisfies  $2m \le N \le M$







| Data (  | Chara        | cteri | stics | 5        |     |     |
|---------|--------------|-------|-------|----------|-----|-----|
| Problem | Training Set |       |       | Test Set |     |     |
|         | Total        | Pos   | Neg   | Total    | Pos | Neg |
| KRK     | 10000        | 33%   | 67%   | 10000    | 33% | 67% |
| Tag     | 1000         | 53%   | 47%   | 10000    | 52% | 48% |



| - | Results    |          |                             |          |          |  |
|---|------------|----------|-----------------------------|----------|----------|--|
|   | Algorithm  | KI       | λK                          | Tag      |          |  |
|   |            | Acc. (%) | $\mathrm{Time}(\mathbf{s})$ | Acc. (%) | Time (s) |  |
|   |            |          |                             | 1        |          |  |
|   | CProgol    | 99.67    | 3634                        | 68.35    | 41979    |  |
|   | CProgol+SS | 99.67    | 995                         | 69-80    | 22011    |  |
|   | CProgol+LW | 99.67    | 284                         | 68.60    | 25229    |  |



| Results V   | Vith Pe  | ssimis                      | tic Est  | imate    |  |
|-------------|----------|-----------------------------|----------|----------|--|
| Algorithm   | KI       | ₹K                          | Tag      |          |  |
|             | Acc. (%) | $\mathrm{Time}(\mathbf{s})$ | Acc. (%) | Time (s) |  |
| CProgol     | 99.68    | 3634                        | 68.35    | 41978    |  |
| CProgol+SS  | 99.68    | 1218                        | 69.80    | 22010    |  |
| CProgol+PSS | 99.68    | 1747                        | 68.49    | 29270    |  |











# Pre-dominant Drawback Lack of directions for selecting a sample size best suited for problem Methods adopted here domain independent





### A study of two sampling methods for analyzing large datasets with ILP

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Presented by: Anand Sivaraman Comments by: Sachin Sharma

#### Noise Problem in Windowing

Basic Idea :

Good Rule→ misclassifies noisy examples → noisy examples added to window → noise in learning window >DATA

#### Example....

- total examples = 11000 *with 10% noise*
- "Correct theory" derived using 1000 examples
- *next* : around 1000 examples will be misclassified with this theory
- Next window will have > 50% noise

#### Solution....

Noise-Tolerant(Examples, InitSize, MaxIncSize) Train = RandomSample(Examples, InitSize) Theory = Φ Repeat NewTheory = findNewTheory(Train) for Rule *in* NewTheory EvaluateRule(Examples) NewTr = Train NewEx = Examples

```
\begin{array}{l} \mbox{Candidates} = \Phi \\ \mbox{if}(\mbox{Significant}(\mbox{Rule},\mbox{Examples}) \\ \mbox{Theory} = \mbox{Theory} + \mbox{Rule} \\ \mbox{NewTr} = \mbox{NewTr} - \mbox{Cover}(\mbox{Rule},\mbox{Train}) \\ \mbox{NewEx} = \mbox{NewEx} - \mbox{Cover}(\mbox{Rule},\mbox{Examples}) \\ \mbox{else} \\ \mbox{Candidates} = \mbox{Candidates} + \mbox{Cover}(\mbox{Rule},\mbox{Examples}) \\ \mbox{for each Positive}``example" not `Covered' by NewTheory \\ \mbox{Candidates} = \mbox{Candidates} + \mbox{``example"}` \\ \mbox{Examples} = \mbox{NewEx} + \mbox{Candidates} \\ \mbox{Train} = \mbox{NewTr} + \mbox{RandomSample}(\mbox{Example},\mbox{MaxIncSize}) \\ \mbox{Until Candidates} = \mbox{} \Phi \end{array}
```

#### A study of two sampling methods for analysing large datasets with ILP

By ASWIN SRINIVASAN oxford university computing laboratory

#### **Covering Procedure**

 $generalise(B, I, \mathcal{L}, E): \mbox{ Given background knowledge } B, hypothesis constraints I, a finite training set <math display="inline">E=E^+\cup E^-,$  returns a hypothesis H in  $\mathcal{L}$  such that H explains the E,

- 1. i = 0
- 2.  $E_i^+ = E^+, H_i = \emptyset$ 3. if  $E_i^+ = \emptyset$  return  $H_i$  otherwise continue
- 4. increment i
- 5.  $Train_i = E_{i-1}^+ \cup E^-$
- 6. Let  $e_i^+ \in E_{i-1}^+$ ,  $D_i$  be the "best" definite clause in  $\mathcal{L}$  s.t.  $B \cup H_{i-1} \cup \{D_i\} \models \{e_i^+\}, B \cup H_{i-1} \cup \{D_i\} \not\models \Box, B \cup H_{i-1} \cup \{D_i\} \not\models \Box$ , and  $B \cup H_{i-1} \cup \{D_i\} \cup I \not\models \Box$
- $\begin{array}{l} B \cup H_{i-1} \cup \{D_i\} \cup H_{i} = 1 \\ T, \quad H_i = H_{i-1} \cup \{D_i\} \\ 8, \quad E_p = \{e_p: e_p \in E_{i-1}^+ \text{ s.t. } B \cup H_i \models \{e_p\}\}, \\ 9, \quad E_i^+ = E_{i-1}^+ \backslash E_p \end{array}$
- 10. Go to Step 3

#### Partial Correctness

Show an explanation H that has sufficient properties

1) for each  $D_i$  in  $H, B \cup \{D_i\} e_1 \vee e_2 \vee e_3...,$  where  $\{e_1, e_2, ...\} \in E +$ 2)  $B \cup H$  entails E<sup>\*</sup> Prove property 1: From step 6 the above property is satisfied by all clauses Prove property 2 : By invariant method C1- before commencing step 1 C2 - before going around the loop C3- on termination · Assertions for each check point A: - input B, I, L, E is legal  $A_2\text{-}B\cup H \text{-} entails \, E^*\setminus FN$ A<sub>2</sub> - B ∪ H entails E\* Each time path  $(Ci) \rightarrow (Cj)$  traversed we have to show if Ai is true Aj is true

#### Partial Correctness

•  $(C1) \rightarrow (C2)$  $H_i = H_0 = \phi$  and  $E_i^+ = E_0^+ = E^+$  thus  $E^+ \setminus E_i^+ = \phi$ A2 trivially holds  $\bullet\,(\mathrm{C2}) \to (C3)$ if  $A_2: B \cup H_i$  entails  $E^+ \setminus E_i^+$  is true and  $E_i^+ = \phi$  then  $A_3: B \cup H_i$ entails  $E^+$  $\bullet(\mathrm{C2}) \mathop{\rightarrow} (C2)$ On iteration *i* if  $A2 = A_2^i : B \cup H_i$  entails  $E^+ \setminus E_i^+$  is true we have to show on iteration  $i + 1 A_2^{i+1} : B \cup H_i$  entails  $E^+ \setminus E_{i+1}^+$  also holds