

## 3D Vectors with Mathematica

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Vectors are defined as rows:

**A** = {a1, a2, a3};

**B** = {b1, b2, b3};

Scalar multiplication:

**c \* A**

{a1 c, a2 c, a3 c}

Dot products can be done with two different commands:

**Dot[A, B]**

**A.B**

a1 b1 + a2 b2 + a3 b3

a1 b1 + a2 b2 + a3 b3

Vector lengths are computed with the **Norm** command.

**Norm[A]**

$\sqrt{\text{Abs}[a1]^2 + \text{Abs}[a2]^2 + \text{Abs}[a3]^2}$

Vector cross products are computed with two different commands:

**Cross[A, B]**

**A x B**

{-a3 b2 + a2 b3, a3 b1 - a1 b3, -a2 b1 + a1 b2}

{-a3 b2 + a2 b3, a3 b1 - a1 b3, -a2 b1 + a1 b2}

The **MatrixForm** command displays vectors in column format:

**MatrixForm[%]**

$$\begin{pmatrix} -a3 b2 + a2 b3 \\ a3 b1 - a1 b3 \\ -a2 b1 + a1 b2 \end{pmatrix}$$

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Example: Compute the Dot and Cross Products of A = (1, 3, 2) and B = (2, 3, 5). Evaluate the following commands to see the result.

**A** = {1, 3, 2};

**B** = {2, 3, 5};

**Dot[A, B]**

**Cross[A, B]**

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Verify that the cross product of A and B is always orthogonal to A and B, by showing that  $(\mathbf{A} \times \mathbf{B}) \cdot \mathbf{A} = 0$  and  $(\mathbf{A} \times \mathbf{B}) \cdot \mathbf{B} = 0$ .

**A = {a1, a2, a3};**

**B = {b1, b2, b3};**

**Dot[Cross[A, B], A]**

$a_3 (-a_2 b_1 + a_1 b_2) + a_2 (a_3 b_1 - a_1 b_3) + a_1 (-a_3 b_2 + a_2 b_3)$

**Simplify[%]**

0

**Dot[Cross[A, B], B]**

$(-a_2 b_1 + a_1 b_2) b_3 + b_2 (a_3 b_1 - a_1 b_3) + b_1 (-a_3 b_2 + a_2 b_3)$

**Simplify[%]**

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